

Persephone Mini/MicroFloppy Disk Controller

The document itself begins on the next page.

Document source:

Original backup tapes owned by Dutchman2000, obtained by Atarimania.

Documentary research and PDF layout by Laurent Delsarte.

Note that these backup tapes contain A LOT of information spread out in many folders, meaning it will take time to process the important bits.

Document identification:

| | |
|--------------------------------------|--|
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| Tags: | #Atari #8bit #6502 #400 #800 #1200XL #600XL #800XL #1400XL #1450XLD #810 #815 #1050 #1050CR #1055 #SIO #Intel8050 #MCS-48 #WD1770 |

Comments:

This is the printout of the original source code, fully commented.

What makes this document so interesting are all these valuable comments, which outline all the additional supported features compared to the existing Atari 810, 815 and 1050 5¼-inch floppy disk drives. It concerns a universal driver that can operate with the unreleased Atari 1050CR ("Cost Reduced") 5¼-inch floppy disk drive, as well as with the also unreleased Atari 1055 3½-inch floppy disk drive.

Support is provided for single- or double-sided drives; for SD, 2D (1050 dual density), and DD density formats; and sector sizes of either 128 or 256 bytes. There's also an option to double the communication speed of the SIO port to 38,400 baud. Not all combinations are supported, but everything is clearly explained.

Additionally, I'm offering a companion .ZIP file to download, containing all the contents of the directory – around thirty files in total.

Produced with ATARI CAMAC Assembler.

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Persephone Mini/MicroFloppy Disk Controller

ATARI CAMAC Assembler Ver 1.0A Page 1
PERSEPHONE MINI/MICROFLOPPY DISK CONTROLLER D1:PERSEPH.ASM
DOCUMENTATION

```
0000      LIST -I,-M,-G,R

**      FUNCTION
*
*      This program is the controller for the Atari 1050 CR (cost
*      reduced) mini floppy disk drive and for a possible future
*      micro floppy disk drive. It resides in the ROM of an
*      Intel 8050 microcontroller. Its function is to accept
*      commands from the Atari serial bus and to execute them by
*      driving a Western Digital 1770 FDC chip.

**      MODS
*
*      Original Author Mike Barall 1984-09-11
*      Winner           1984-11-15

**      HARDWARE CONFIGURATION
*
*      The clock rate is 8 MHz, which gives a time of 1.875 us per
*      machine cycle.

*      P10 and P11 select a register in the 1770 chip:
*          P11 P10      Register
*          0   0       Status or Command
*          0   1       Track
*          1   0       Sector
*          1   1       Data

*      P12 is connected to the INTRQ line of the 1770

*      P13 selects FM (1) or MFM (0)

*      P14 is connected to the 1770 Master Reset pin (0 = reset).
*      The controller holds P14 low for 500 us.

*      P15 is connected to the 1770 R/W pin (1 = read, 0 = write).

*      P16 is the side select output (0 = side 0, 1 = side 1).
*      The controller delays 500 us after changing sides. P16 is
*      externally tied to ground if the drive has only one head.

*      P17 is connected to the serial bus data in line (drive to
*      computer). This line is normally high. Note: P17 is the
*      inverse of the SID line.

*      P20 through P24 have no external connections. They are used by
*      the controller as 5 bits of RAM.

*      P25 has no external connection on a mini floppy and is externally
*      grounded on a microfloppy. In the former case, P25 is used as
*      one bit of RAM.

*      P26 and P27 are connected to the device select switches. They
*      select this drive's unit number, as follows:
```

```
*          P27 P26      Unit Number
*          0   0       1
*          0   1       2
*          1   1       3
*          1   0       4

*      INT is connected to the serial bus command line. This line is
*      normally high, and is low during the transmission of a
*      command frame.

*      T0 is connected to the serial bus data out line (computer to
*      drive). Note: T0 is the inverse of the SOD line.

*      T1 is connected to the DRQ line of the 1770. A high on this
*      line indicates that the 1770 data register is full (on a
*      read) or empty (on a write).

*      DB0-DB7 (the external data bus) are connected to the 1770
*      data bus.

**      MEMORY ALLOCATION

*      F0 = SIO fast mode enable/disable (1 = enabled).

*      F1 = Retry flag (1 = retry in progress).

*      P20, P21, P22 = Current activity:
*
*          P22 P21 P20
*          0   0   0     Idle
*          0   0   1     Get sector
*          0   1   0     Put sector without verify
*          0   1   1     Put sector with verify
*          1   0   0     Write option table
*          1   0   1     Miscellaneous disk operation
*          1   1   0     Not used
*          1   1   1     Other

*      P23 = Head position known flag (1 = position known).

*      P24, P25 = Current configuration:
*
*          P25 P24
*          1   0     SS/SD (FM, 128 bytes per sector)
*          1   1     SS/2D (MFM, 128 bytes per sector)
*          0   0     SS/DD (MFM, 256 bytes per sector)
*          0   1     DS/DD (MFM, 256 bytes per sector)
*
*      For micro floppies, only the SS/DD and DS/DD modes are possible,
*      and there are sixteen sectors per track.

**      COMMANDS

* 52      GET SECTOR
```

```
*      Read the specified logical sector.  
* 50   PUT SECTOR WITHOUT VERIFY  
*  
*      Write the specified logical sector.  
* 57   PUT SECTOR WITH VERIFY  
*  
*      Write the specified logical sector and then re-read it to  
*      verify that it was written correctly.  
* 53   STATUS  
*  
*      Return a 4-byte status block.  
* 21   FORMAT  
*  
*      Format the diskette in the current configuration.  
* 22   DUAL DENSITY FORMAT  
*  
*      Format the diskette in SS/2D mode. Valid only when the drive  
*      is configured to SS/SD or SS/2D.  
* 4E   GET OPTION TABLE  
*  
*      Return a 12-byte option block.  
* 4F   PUT OPTION TABLE  
*  
*      Accept a 12-byte option block and change to the indicated  
*      configuration.  
* 48   SET SIO SPEED  
*  
*      Change SIO baud rate to the rate specified by auxiliary byte  
*      #1 (00 = 19200 baud, 01 = 38400 baud).  
* 72   GET COPY PROTECTION SECTOR  
*  
*      Step to the track number (0-39) specified by auxiliary byte #1  
*      on the first side of the disk and read sector F7.  
  
** STATUS BLOCK FORMAT  
*  
*      Byte 1: Controller status  
*          Bit 0 = 1 Invalid command frame  
*          Bit 1 = 1 Invalid data frame  
*          Bit 2 = 1 Operation Unsuccessful  
*          Bit 3 = 1 Write protected (valid only after a write)  
*          Bit 4 = 1 Motor on  
*          Bits 5-7 = Device configuration  
*              7 6 5  
*                  0 0 0  SS/SD  
*                  0 0 1  SS/DD  
*                  0 1 0  Reserved
```

```
*          0 1 1  Reserved
*          1 0 0  SS/2D
*          1 0 1  DS/DD
*          1 1 0  Reserved
*          1 1 1  Reserved
*
*          Byte 2 = 1770 status register (inverted).
*
*          Byte 3 = FORMAT timeout (= $78).
*
*          Byte 4 = Zero.

**        OPTION TABLE FORMAT
*
*          Byte 1 = Number of tracks (= 28).
*
*          Byte 2 = Step rate (= 00).
*          00 = 6 ms
*          01 = 12 ms
*          02 = 20 ms
*          03 = 30 ms
*
*          Byte 3 = Number of sectors per track (high).
*          Byte 4 = Number of sectors per track (low).
*
*          Byte 5 = Number of sides:
*          00 = single sided
*          01 = double sided
*
*          Byte 6 = Recording mode:
*          00 = FM
*          04 = MFM
*
*          Byte 7 = Number of bytes per sector (high).
*          Byte 8 = Number of bytes per sector (low).
*
*          Byte 9 = Drive present:
*          00 = not on line
*          01 = on line
*
*          Byte 10 = SIO bus speed:
*          41 = 19200 baud
*          48 = 38400 baud
*
*          Byte 11 = Reserved.
*          Byte 12 = Reserved.
*
*
*          NOTE: Bytes 1, 2, 3, 9, 10, 11, and 12 are ignored by the PUT
*          OPTION TABLE command. The remaining bytes are used to set
*          the drive configuration, as follows:
*
*          IF bytes 5-6 = 00 and 00 AND the drive is a mini floppy,
*          THEN set SS/SD configuration;
*          ELSE IF bytes 4-8 = 1A, 00, 04, 00, and 80 respectively,
*                  AND the drive is a mini floppy,
```

```
*      THEN set SS/2D configuration;
*      ELSE IF bytes 5-6 = 00 and 04 respectively,
*      THEN set SS/DD configuration;
*      ELSE IF bytes 5-6 = 01 and 04 AND drive has two heads,
*      THEN set DS/DD configuration;
*      ELSE return error and leave configuration unchanged.

** SIO TIMING

* At 19200 baud, one bit time is 27.78 CPU cycles (which we
* take as 28 CPU cycles). At 38400 baud, one bit time is
* 13.89 CPU cycles (which we take as 14 CPU cycles).

* The controller is responsible for generating the following
* delays:
*
* t2 = delay between raising of COMMAND and transmission of ACK
*      t2 min = 0 us
*      t2 max = 16 ms
*
* t4 = delay between transmission of the last bit of the data
*      frame by the computer and transmission of first bit of
*      ACK by the drive
*      t4 min = 850 us
*      t4 max = 16 ms
*
* t5 = delay between transmission of last bit of ACK and
*      transmission of first bit of CMPLT
*      t5 min = 250 us (19200 baud), 750 us (38400 baud)
*      t5 max = 255 sec (handler dependent)

* The computer generates the following delays:
*
* t0 = delay between lowering of COMMAND and transmission of
*      first bit of command frame
*      t0 min = 750 us
*      t0 max = 1600 us
*
* t1 = delay between transmission of last bit of command frame
*      and raising of COMMAND
*      t1 min = 650 us
*      t1 max = 950 us
*
* t3 = delay between receipt of last bit of ACK and transmission
*      of first bit of data frame by the computer
*      t3 min = 1000 us
*      t4 max = 1800 us
```

0000

```
**      TIMING EQUATES

= 0177  CLOCK  EQU    375          ;CPU CYCLE TIME IN UNITS OF 5 NS
= 0108  US500  EQU  [[50000/CLOCK]-1]*2   ;LOOP COUNT FOR 500 US DELAY
= 0068  US200  EQU  [[20000/CLOCK]-1]*2   ;LOOP COUNT FOR 200 US DELAY
= 013E  US600  EQU  [[60000/CLOCK]-1]*2   ;LOOP COUNT FOR 600 US DELAY

= 009A  TRIP   EQU    154          ;TIMER OVERFLOW INTERVAL IN UNITS OF
                                ;100 US (= CLOCK*32*256*5/100000)

= 0040  SEC1   EQU    10000/TRIP    ;TRIP COUNT FOR 1 SECOND DELAY
= 00C2  SEC3   EQU    30000/TRIP    ;TRIP COUNT FOR 3 SECOND DELAY
= 0010  MS240  EQU  [2400/TRIP]+1  ;TRIP COUNT FOR 240 MS DELAY
= 0095  MS2300 EQU  23000/TRIP    ;TRIP COUNT FOR 2.3 SECOND DELAY

**      WD1770 REGISTER SELECT EQUATES

= 00DC  WDCLR  EQU    $DC          ;MASK TO CLEAR REGISTER SELECTION

= 0020  WDRSTA EQU    $20          ;READ STATUS REGISTER
= 0000  WDWCMD  EQU    $00          ;WRITE COMMAND REGISTER
= 0021  WDRTRK  EQU    $21          ;READ TRACK REGISTER
= 0001  WDWTRK  EQU    $01          ;WRITE TRACK REGISTER
= 0022  WDRSEC  EQU    $22          ;READ SECTOR REGISTER
= 0002  WDWSEC  EQU    $02          ;WRITE SECTOR REGISTER
= 0023  WDRDAT  EQU    $23          ;READ DATA REGISTER
= 0003  WDWDAT  EQU    $03          ;WRITE DATA REGISTER

**      WD1770 COMMANDS

= 0002  SRATE   EQU    $02          ;STEP RATE CODE

= 0080  RDSEC   EQU    $80          ;READ SECTOR
= 00A2  WRSEC   EQU    $A2          ;WRITE SECTOR WITHOUT PRECOMP
= 00A0  WRSECP  EQU    $A0          ;WRITE SECTOR WITH PRECOMP
= 00C4  RDADR   EQU    $C4          ;READ ADDRESS WITH 30 MS DELAY
= 00F6  WRTRK   EQU    $F6          ;WRITE TRACK WITHOUT PRECOMP
= 00F4  WRTRKP  EQU    $F4          ;WRITE TRACK WITH PRECOMP
= 00D0  FRCINT  EQU    $D0          ;FORCE INTERRUPT
= 0002  REST    EQU    $00 OR SRATE ;RESTORE
= 000A  RESTF   EQU    $08 OR SRATE ;RESTORE W/O MOTOR SPIN-UP
= 0012  SEEK    EQU    $10 OR SRATE ;SEEK

= 00F7  IMPSEC  EQU    $F7          ;'IMPOSSIBLE' SECTOR NUMBER

**      CONTROL LINES FOR PORT 1

= 0004  INTRQ   EQU    $04          ;1770 INTERRUPT REQUEST
= 0008  DDEN    EQU    $08          ;1770 DOUBLE DENSITY ENABLE
= 0010  MR      EQU    $10          ;1770 MASTER RESET
= 0040  SSO     EQU    $40          ;SIDE SELECT OUTPUT
```

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PERSEPHONE MINI/MICROFLOPPY DISK CONTROLLER D1:PERSEPH.ASM
EQUATES

| | | | | |
|----------------------------------|--------|-----|------|---------------------------------------|
| = 0080 | SID | EQU | \$80 | ;SERIAL INPUT DATA LINE |
| = 0004 | INP1 | EQU | \$04 | ;INPUT LINES ON PORT 1 |
| ** CONTROL LINES FOR PORT 2 | | | | |
| = 00C0 | UNITMK | EQU | \$C0 | ;MASK FOR UNIT NUMBER SWITCHES |
| = 0000 | UNIT1 | EQU | \$00 | ;UNIT 1 SELECT |
| = 0040 | UNIT2 | EQU | \$40 | ;UNIT 2 SELECT |
| = 00C0 | UNIT3 | EQU | \$C0 | ;UNIT 3 SELECT |
| = 0080 | UNIT4 | EQU | \$80 | ;UNIT 4 SELECT |
| = 00C0 | INP2 | EQU | \$C0 | ;INPUT LINES FOR PORT 2 |
| ** COMMUNICATION VALUES | | | | |
| = 0041 | ACK | EQU | \$41 | ;ACKNOWLEDGE |
| = 0043 | COMPLT | EQU | \$43 | ;SUCCESSFUL COMPLETION |
| = 0045 | ERROR | EQU | \$45 | ;COMPLETION WITH ERROR |
| = 004E | NAK | EQU | \$4E | ;NOT ACKNOWLEDGE |
| = 0048 | HSACK | EQU | \$48 | ;FAST MODE ACKNOWLEDGE |
| ** ACTIVITY CODES | | | | |
| = 00F8 | ACLR | EQU | \$F8 | ;MASK TO CLEAR ACTIVITY CODE |
| = 0000 | AIDLE | EQU | \$00 | ;IDLE |
| = 0001 | AGET | EQU | \$01 | ;GET SECTOR |
| = 0002 | APUT | EQU | \$02 | ;PUT SECTOR |
| = 0003 | APUTV | EQU | \$03 | ;PUT SECTOR WITH VERIFY |
| = 0004 | APOPT | EQU | \$04 | ;PUT OPTION TABLE |
| = 0005 | AMISC | EQU | \$05 | ;MISCELLANEOUS DISK OPERATION |
| = 0007 | AOTHER | EQU | \$07 | ;OTHER |
| ASSERT AIDLE=0 ;LEGAL ASSUMPTION | | | | |
| ** HEAD POSITION KNOWN BIT | | | | |
| = 0008 | HKNOWN | EQU | \$08 | ;HEAD POSITION KNOWN |
| ** CONFIGURATION CODES | | | | |
| = 00CF | CFCLR | EQU | \$CF | ;MASK TO CLEAR CONFIGURATION CODE |
| = 0020 | SECTSZ | EQU | \$20 | ;MASK TO READ SECTOR SIZE BIT |
| = 0020 | CFSSSD | EQU | \$20 | ;SS/SD |
| = 0030 | CFSS2D | EQU | \$30 | ;SS/2D |
| = 0000 | CFSSDD | EQU | \$00 | ;SS/DD |
| = 0010 | CFDSDD | EQU | \$10 | ;DS/DD |
| ** INTERNAL RAM ADDRESSES | | | | |
| = 00FF | BSL256 | EQU | \$FF | ;BAD SECTOR LIST FOR 256-BYTE SECTORS |

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PERSEPHONE MINI/MICROFLOPPY DISK CONTROLLER D1:PERSEPH.ASM
EQUATES

```
= 00FB    CSTAT   EQU    BSL256-4      ;CONTROLLER STATUS
= 00FA    HSTAT   EQU    CSTAT-1       ;HARDWARE STATUS
= 00F9    CDEVIC  EQU    HSTAT-1       ;COMMAND FRAME DEVICE NUMBER
= 00F8    CCOMND  EQU    CDEVIC-1      ;COMMAND FRAME COMMAND
= 00F7    CAUX1   EQU    CCOMND-1      ;COMMAND FRAME AUXILIARY #1
= 00F6    CAUX2   EQU    CAUX1-1       ;COMMAND FRAME AUXILIARY #2
= 00F5    R0SAV   EQU    CAUX2-1       ;SAVE AREA FOR R0
= 00F4    R1SAV   EQU    R0SAV-1       ;SAVE AREA FOR R1
= 00F3    R2SAV   EQU    R1SAV-1       ;SAVE AREA FOR R2
= 00F2    R3SAV   EQU    R2SAV-1       ;SAVE AREA FOR R3
= 00F1    R4SAV   EQU    R3SAV-1       ;SAVE AREA FOR R4
= 00F0    R5SAV   EQU    R4SAV-1       ;SAVE AREA FOR R5

= 007F    BSL128  EQU    $7F          ;BAD SECTOR LIST FOR 128-BYTE SECTORS
```

0000

```
**      JDRQ - JUMP IF DRQ
JDRQ  MACRO  ADDR
%L    JT1    %1
      ENDM

**      JNDRQ - JUMP IF NOT DRQ
JNDRQ MACRO  ADDR
%L    JNT1   %1
      ENDM

**      SETREG - SET WD1770 REGISTER
SETREG MACRO  REG
%L    ANLI   P1,WDCLR
        ORLI   P1,WD%1
      ENDM

**      JSOD - JUMP IF SERIAL OUTPUT DATA HIGH
JSOD  MACRO  ADDR
%L    JNT0   %1
      ENDM

**      JNSOD - JUMP IF SERIAL OUTPUT DATA LOW
JNSOD MACRO  ADDR
%L    JT0    %1
      ENDM

**      CLRSID - CLEAR SERIAL INPUT DATA
CLRSID MACRO
%L    ORLI   P1,SID
      ENDM

**      SETSID - SET SERIAL INPUT DATA
SETSID MACRO
%L    ANLI   P1,$FF-SID
      ENDM

**      WINT - WAIT FOR INTERRUPT
WINT  MACRO
%L    MM%K  JUMP   MM%K
```

```
        ENDM

**      LNGJMP - LONG JUMP
LNGJMP MACRO  ADDR
%L      DB      $E5 OR [[[%1]&$0800]/$80]
        JUMP    %1
        ENDM

**      PAUSE - DELAY FOR A FEW CPU CYCLES
PAUSE  MACRO  REGISTER,CYCLES
%L
        IF      [%2]&1
        NOPP
        ENDIF
        IF      [[%2]&$FFFE]=2
        NOPP
        NOPP
        ENDIF
        IF      [%2]>3
        MOVI    %1,[[%2]/2]-1
        DJNZ    %1,MM%K
        ENDIF
        ENDM

**      LNGCAL - LONG CALL
LNGCAL MACRO  ADDR
%L      DB      $E5 OR [[[%1]&$0800]/$80]
        CALL    %1
        DB      $E5 OR [[[*]&$0800]/$80]
        ENDM
```

```
0000          ORG      $1000
0000 = 1000
              **      RESET COMES HERE
1000          LNGJMP  RESET           ;GO DO RESET ROUTINE
              **
              **      EXTERNAL INTERRUPT COMES HERE
              ASSERT  *=+$1003
1003          SEL      RB0
1004          LNGJMP  COMPRO          ;GO TO COMMAND FRAME PROCESSOR
              **
              **      TIMER INTERRUPT COMES HERE
              ASSERT  *=+$1007
;
;      THIS CODE HANDLES TIMEOUTS WHICH OCCUR DURING RECEPTION OF
;      A DATA FRAME FROM THE SERIAL BUS.
;
1007          SEL      MB0
1008          DIS      TCNTI
1009          STOP    TCNT
100A          CALL    ENABLE          ;RESET INTERRUPT-IN-PROGRESS FLIP-FLOP
;
;      JUMP     INVDF             ;INDICATE INVALID DATA FRAME
;
              **      INVDF - PROCESS INVALID DATA FRAME
100C          INVDF
100C
100E          MOVI    R0,CSTAT
              MOVI    XR0,$02          ;INVALID DATA FRAME
;
;      JUMP     IDLE              ;GO TO IDLE STATE
;
              **      IDLE - ENTER IDLE STATE
1010          IDLE
1010          MOVI    R7,SEC3          ;3 SECOND TRIP COUNT
1012          STRT    T
1013          ANLI    P2,ACLR          ;INDICATE IDLE STATE
1015          EN      I
1016          IDLE1
1016          JTF     IDLE2          ;IF TIMER TRIPPED
1018          JUMP    IDLE1          ;WAIT FOR TRIP
101A          IDLE2
101A          DJNZ    R7,IDLE1          ;IF 3 SECONDS NOT ELAPSED
101C          IDLE4
101C          SETREG  RSTA
1020          MOVX    A,XR0           ;READ THE STATUS REGISTER
1021          CPL     A
1022          JB7     IDLE5          ;IF MOTOR OFF
```

```
;      MOTOR TIMED OUT, SO RESET 1770 TO FORCE MOTOR OFF

1024      IDLE3      ANLI    P2,$FF-HKNOWN ;INDICATE HEAD POSITION UNKNOWN
1024          ANLI    P1,$FF-MR   ;SEND RESET SIGNAL
1026      IDLES5     WINT      ;WAIT FOR INTERRUPT
1028
1028      ;      ENTRY POINT FOR RETURN FROM INTERRUPT

102A      INTRET     EN       I
102A          IN       A,P1
102B          ANLI    A,MR
102C          JZ       IDLES5 ;IF RESET IS LOW
102E          MOV      A,R7
1030          JNZ      IDLE1  ;IF TIMING IN PROGRESS
1031          JUMP    IDLE4   ;MAKE SURE MOTOR IS OFF

**      ENABLE - RESET THE INTERRUPT-IN-PROGRESS FLIP-FLOP

1035      ENABLE     RETR
1035

**      COMPRO - COMMAND FRAME PROCESSOR

1036      COMPRO
1036      ;      GET OFF THE SERIAL BUS

1036      SETSID
1036      ;      RESET THE INTERRUPT-IN-PROGRESS FLIP-FLOP

1038      DIS       TCNTI
1039      DIS       I
103A      CALL     ENABLE

1036      ;      CHECK TO SEE IF WE WERE IN MID-OPERATION

103C      IN        A,P2
103D      ANLI    A,$FF-ACLR
103F      JZ       COM1   ;IF NOT IN MID-OPERATION

1036      ;      CONSTRUCT PSEUDO-STATUS IN CSTAT

1041      MOVI    R0,CSTAT
1043      MOVI    XR0,$04   ;STATUS FOR UNSUCCESSFUL OPERATION

1041      ;      SET UP MOTOR TIMEOUT

1045      MOVI    R7,SEC3  ;3 SECOND TRIP COUNT
1047      STRT    T        ;START THE TIMER GOING

1041      ;      INDICATE IDLE STATE
```

```
1048      ANLI    P2,ACLR
;
; INITIATE A FORCED INTERRUPT TO THE 1770 IF NECESSARY
104A      XRLI    A,APOPT
104C      JZ      COM1      ;IF PUT OPTION TABLE
104E      XRLI    A,APOPT XOR AOTHER
1050      JZ      COM1      ;IF OTHER NON-DISK OPERATION
1052      IN      A,P1
1053      ANLI    A,MR
1055      JZ      COM1      ;IF RESET IS LOW
1057      SETREG WCMD
105B      MOVI    A,FRCINT
105D      MOVX    XR0,A
;
; INITIALIZE FOR COMMAND FRAME RECEPTION
105E      COM1
105E      MOVI    R0,CDEVIC   ;STARTING ADDRESS
1060      MOVI    R1,0       ;INIT CHECKSUM
1062      MOVI    R2,5       ;NUMBER OF BYTES
;
; CHECK COMMAND LINE
1064      COM3
1064      JNI     COM5      ;IF COMMAND LINE LOW
1066      COM4
1066      JUMP    INTRET    ;COMMAND FRAME SCREWED UP, RETURN
;
; STORE BYTE OF COMMAND FRAME INTO RAM AND UPDATE CHECKSUM
1068      COM2
1068      MOV     XR0,A
1069      DECR   R0
106A      ADD    A,R1
106B      ADDCI  A,0
106D      MOV    R1,A
106E      PAUSE   R3,12
1072      JNSOD  COM12     ;IF STOP BIT IS BAD
;
; WAIT FOR START BIT
1074      COM5
1074      JSOD   COM3      ;IF START BIT NOT DETECTED
;
; INITIALIZE FOR DATA BYTE RECEPTION
1076      MOVI    A,$80
1078      PAUSE   R3,16      ;DELAY 16 CPU CYCLES
;
; LOOP TO READ IN BYTE BIT-BY-BIT
107C      COM6
107C      PAUSE   R3,19      ;DELAY 19 CPU CYCLES
1081      CLR     C
```

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 PERSEPHONE MINI/MICROFLOPPY DISK CONTROLLER D1:PERSEPH.ASM
 COMMAND FRAME PROCESSOR

```

1082          JNSOD  COM7           ;IF BIT IS A ZERO
1084          CPL    C
1085          JUMP   COM8
1087          COM7
1087          PAUSE  R3,3         ;EQUALIZE TIME OF THE TWO PATHS
108A          COM8
108A          RRC    A           ;SHIFT IN THE BIT
108B          JNC    COM6         ;IF NOT DONE WITH 8 BITS

;      CHECK CHECKSUM

108D          DJNZ   R2,COM2       ;IF CHECKSUM NOT RECEIVED YET
108F          XRL    A,R1
1090          JNZ    COM12        ;IF CHECKSUM DOESN'T MATCH
1092          PAUSE  R3,15
1097          JNSOD COM12        ;IF STOP BIT IS WRONG
1099          JNI    COM11        ;IF COMMAND LINE IS STILL LOW
109B          JUMP   INTRET

;      CHECK TO SEE IF COMMAND IS FOR US

109D          COM11
109D          MOVI   R1,$31        ;DEVICE NUMBER FOR UNIT #1
109F          IN     A,P2         ;READ DEVICE SELECT SWITCHES
10A0          ANLI   A,UNITMK      ;SELECT UNIT # BITS
10A2          XRLI   A,UNIT1
10A4          JZ    COM10         ;IF UNIT 1
10A6          INCR   R1
10A7          XRLI   A,UNIT2 XOR UNIT1
10A9          JZ    COM10         ;IF UNIT 2
10AB          INCR   R1
10AC          XRLI   A,UNIT3 XOR UNIT2
10AE          JZ    COM10         ;IF UNIT 3
10B0          INCR   R1         ;ELSE, MUST BE UNIT 4
10B1          COM10
10B1          MOVI   R0,CDEVIC
10B3          MOV    A,XR0        ;BRING IN DEVICE NUMBER
10B4          XRL    A,R1
10B5          JZ    COM13         ;IF COMMAND IS FOR US
10B7          COM12
10B7          JNI    COM12        ;WAIT FOR COMMAND TO GO HIGH
10B9          JUMP   INTRET

;      BRANCH TO VARIOUS COMMAND ROUTINES

10BB          COM13
10BB          JUMP   COMLK
10BD = 1100    ASSERT *<=$1100
1100          ORG    $1100
1100          COMLK

1100          DECR   R0
1101          MOV    A,XR0        ;BRING IN COMMAND
1102          XRLI   A,$52
1104          JZ    COM28
1106          XRLI   A,$72 XOR $52
1108          JNZ    COM20

```

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 PERSEPHONE MINI/MICROFLOPPY DISK CONTROLLER D1:PERSEPH.ASM
 COMMAND FRAME PROCESSOR

```

110A      COM28
110A      ORLI   P2,AGET      ;SET ACTIVITY CODE FOR GET
110C      LNGJMP GET        ;GET SECTOR
110F      COM20
110F      XRLI   A,$50 XOR $72
1111      JNZ    COM21
1113      ORLI   P2,APUT      ;SET ACTIVITY CODE FOR PUT
1115      LNGJMP PUT        ;PUT SECTOR
1118      COM21
1118      XRLI   A,$57 XOR $50
111A      JNZ    COM22
111C      ORLI   P2,APUTV     ;SET ACTIVITY CODE FOR PUT/VERIFY
111E      LNGJMP PUTV       ;PUT/VERIFY SECTOR
1121      COM22
1121      XRLI   A,$53 XOR $57
1123      JNZ    COM23
1125      ORLI   P2,AOTHER    ;ACTIVITY CODE FOR 'OTHER'
1127      LNGJMP STAT       ;STATUS
112A      COM23
112A      XRLI   A,$21 XOR $53
112C      JNZ    COM24
112E      ORLI   P2,AMISC     ;ACTIVITY CODE FOR MISCELLANEOUS
1130      LNGJMP FMT        ;FORMAT
1133      COM24
1133      XRLI   A,$4E XOR $21
1135      JNZ    COM25
1137      ORLI   P2,AOTHER    ;ACTIVITY CODE FOR 'OTHER'
1139      LNGJMP GOPT       ;GET OPTION TABLE
113C      COM25
113C      XRLI   A,$4F XOR $4E
113E      JNZ    COM26
1140      ORLI   P2,AOPT      ;ACTIVITY CODE FOR PUT OPTION TABLE
1142      LNGJMP POPT       ;PUT OPTION TABLE
1145      COM26
1145      XRLI   A,$48 XOR $4F
1147      JNZ    COM27
1149      ORLI   P2,AOTHER    ;ACTIVITY CODE FOR 'OTHER'
114B      LNGJMP SPEED      ;SET SIO SPEED
114E      COM27
114E      XRLI   A,$22 XOR $48
1150      JNZ    INVCF
1152      IN     A,P2
1153      ANLI   A,SECTSZ
1155      JZ     INVCF      ;IF SECTOR SIZE IS 256
1157      ORLI   P2,AMISC     ;ACTIVITY CODE FOR MISCELLANEOUS
1159      LNGJMP FMTD       ;FORMAT DUAL DENSITY

**      INVCF - PROCESS INVALID COMMAND FRAME

115C      INVCF
115C      MOVI   R0,CSTAT
115E      MOVI   A,$01      ;STATUS FOR INVALID COMMAND FRAME
1160      MOV    XR0,A       ;SAVE IT

1161      MOVI   A,NAK
1163      LNGCAL XBYTE      ;SEND NAK

```

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PERSEPHONE MINI/MICROFLOPPY DISK CONTROLLER D1:PERSEPH.ASM
COMMAND FRAME PROCESSOR

1167 JUMP INTRET ;RETURN

```
1169          **      RESET - POWER ON INITIALIZATION
1169
1169          RESET
1169          DIS    I
116A          DIS    TCNTI
116B          MOVI   A,INP1+WDRSTA+DDEN
116D          OUTL   P1,A
116E          MOVI   A,INP2+CFSSD+AIDLE
1170          OUTL   P2,A
1171          SEL    RB0
1172          CLR    F0      ;INIT TO SLOW MODE
1173          CLR    F1

1174          STOP   TCNT
1175          CLR    A
1176          MOV    T,A
1177          MOVI   R0,MS240
1179          STRT   T
117A          JTF    RESET1      ;CLEAR TIMER OVERFLOW FLAG
117C          RESET1
117C          JTF    RESET2
117E          JUMP   RESET1
1180          RESET2
1180          DJNZ   R0,RESET1      ;IF NOT FINISHED WITH 1/4 SECOND DELAY
1182          STOP   TCNT

1183          MOVI   R0,CSTAT
1185          MOVI   XR0,0      ;INIT CONTROLLER STATUS
1187          EN     I
1188          WINT

;WAIT FOR INTERRUPT
```

118A

```
**      SENDAK - SEND ACKNOWLEDGE
*
*      EXIT CONDITIONS: A & R6 MODIFIED, INTERRUPTS ENABLED,
*      TIMER STOPPED AND CLEARED, TIMER OVERFLOW CLEARED,
*      RETRY FLAG CLEARED

118A      SENDAK
118A          STOP   TCNT
118B          CLR    A
118C          MOV    T,A
118D          JTF    SNDLK1      ;CLEAR TIMER OVERFLOW FLAG
118E          SNDLK1
118F          MOVI   A,HSACK   ;HIGH SPEED ACK
118G          JFO    SNDLK2   ;IF HIGH SPEED ENABLED
118H          MOVI   A,ACK    ;NORMAL ACK
118I          SNDLK2
118J          ;      JUMP   XBYTE    ;SEND BYTE, RETURN

**      XBYTE - SEND A BYTE OVER SERIAL BUS AT 19200 BAUD
*
*      ENTRY CONDITION: BYTE TO BE SENT IN A
*
*      EXIT CONDITION: R6 & A ARE MODIFIED, INTERRUPTS ARE ENABLED,
*      RETRY FLAG CLEARED

1195      XBYTE
1195          CLR    F1      ;CLEAR RETRY FLAG

1196      XBYTE4
1196          JNI    XBYTE4   ;WAIT FOR COMMAND TO GO HIGH
1197          JNI    XBYTE4   ;JUST IN CASE
1198          EN     I        ;RE-ENABLE INTERRUPTS
1199

119B          CLRSID
119C          CLR    C        ;SEND START BIT
119D          CPL    C
119E          PAUSE  R6,3    ;DELAY 3 CPU CYCLES
119F          XBYTE1
119G          PAUSE  R6,18   ;DELAY 18 CPU CYCLES
119H          RRC    A        ;SHIFT OUT NEXT BIT
119I          JC    XBYTE2   ;IF BIT IS A ONE
119J          CLRSID
119K          JUMP   XBYTE3   ;SEND A ZERO
119L          XBYTE2
119M          SETSID
119N          JUMP   XBYTE3   ;SEND A ONE
119O          XBYTE3
119P          JNZ    XBYTE1   ;EQUALIZE THE TIME AROUND BOTH PATHS
119Q          CLR    C
119R          JNZ    XBYTE1   ;IF NOT DONE WITH 8 BITS
119S          RET
```

11B5

```
**      RECV - RECEIVE DATA FRAME
*
*      ENTRY CONDITIONS: (NUMBER OF BYTES TO RECEIVE)-1 IN R0,
*                          TIMER STOPPED AND CLEARED, TIMER OVERFLOW CLEARED
*
*      EXIT CONDITIONS: DATA FRAME IN INTERNAL RAM,
*                         RETRY FLAG CLEARED,
*                         EXIT THRU INVDF IF CHECKSUM ERROR OR TIMEOUT.

11B5 = 1200      ASSERT *<=$1200
                  ORG   $1200

1200      RECV      EN      TCNTI
1200      STRT      T       ;BEGIN TIMEOUT FOR FIRST BYTE
1201      RECV22    JSOD    RECV22   ;WAIT FOR START BIT
1202      CLR       A       ;INIT CHECKSUM
1204      CLR       F1      ;INDICATE LAST BYTE NOT RECEIVED
1205      NOPP
1206      NOPP
1207      NOPP      ;DELAY 2 CPU CYCLES
1208      JUMP     RECV21

;      READ IN THE FIRST [R0] BYTES

120A      RECV5     JNSOD   RECV19   ;IF STOP BIT BAD
120A      RECV1     JSOD    RECV1    ;IF START BIT NOT DETECTED
120C      INCR     R0
120C      MOV      XR0,A   ;PLACE BYTE INTO RAM
120E      DECR     R0
120F      ADD      A,R1
1210      ADDCI    A,0
1211      RECV21    MOV     R1,A   ;UPDATE CHECKSUM
1212      RECV10    CLR     A
1213      MOV      T,A   ;RESET THE TIMER
1214      MOVI     A,$80   ;INIT FOR DATA BYTE RECEPTION
1215
1216
1217

1219      NOPP
1220      NOPP
1221      NOPP
1222      NOPP
1223      NOPP
1224      JFO     RECV6    ;DELAY 6 CPU CYCLES IN FAST MODE
1225      NOPP
1226      NOPP      ;DELAY 8 CYCLES IN SLOW MODE

1221      RECV2     NOPP
1222      NOPP
1223      NOPP
1224      JFO     RECV6    ;DELAY 5 CPU CYCLES IN FAST MODE
1225      NOPP
```

```
1227      NOPP
1228      NOPP
1229      NOPP
122A      NOPP
122B      NOPP
122C      NOPP
122D      NOPP
122E      NOPP
122F      NOPP
1230      NOPP
1231      NOPP
1232      NOPP
1233      NOPP          ;DELAY 19 CYCLES IN SLOW MODE

1234      RCV6
1234      CLR   C
1235      JNSOD RCV3          ;IF BIT IS A ZERO
1237      CPL   C
1238      JUMP  RCV4
123A      RCV3
123A      NOPP
123B      NOPP
123C      NOPP          ;EQUALIZE TIME AROUND BOTH PATHS
123D      RCV4
123D      RRC   A          ;SHIFT IN THE BIT
123E      JNC   RCV2          ;IF NOT DONE WITH 8 BITS
1240      JF0   RCV7          ;DELAY 2 CYCLES IN FAST MODE
1242      NOPP
1243      NOPP
1244      NOPP
1245      NOPP
1246      NOPP
1247      NOPP
1248      NOPP
1249      NOPP
124A      NOPP
124B      NOPP
124C      NOPP
124D      NOPP
124E      NOPP
124F      NOPP          ;DELAY 16 CYCLES IN SLOW MODE

1250      RCV7
1250      JF1   RCV13          ;IF LAST BYTE RECEIVED
1252      DJNZ  R0,RCV5          ;IF MORE BYTES TO DO
1254      JNSOD RCV19          ;IF STOP BIT BAD
1255      ;      BRING IN THE LAST DATA BYTE

1256      RCV8
1256      JSOD  RCV8          ;IF START BIT NOT DETECTED
1258      XCH   A,R1          ;PLACE BYTE INTO RAM
1259      ADD   A,R1
125A      ADDC  A,R0          ;R0 CONTAINS 0
125B      MOV   R0,A          ;UPDATE CHECKSUM
125C      CPL   F1          ;INDICATE LAST BYTE RECEIVED
125D      JUMP  RCV10          ;GO RECEIVE LAST BYTE
```

```
;      COMPARE CALCULATED CHECKSUM TO RECEIVED CHECKSUM

125F      RCV13      CLR    F1          ;CLEAR RETRY FLAG
125F      NOPP
1260      JNSOD     RCV19      ;DELAY 1 CPU CYCLE
1261      ;IF STOP BIT IS BAD
1263      RCV14      JSOD   RCV14      ;WAIT FOR START BIT
1265      STOP     TCNT
1266      DIS      TCNTI
1267      MOV      T,A          ;SAVE LAST BYTE IN TIMER
1268      ADD      A,R0
1269      ADDCI   A,0          ;FINISH CHECKSUM CALCULATION
126B      CLR      C
126C      CPL      C

126D      NOPP
126E      NOPP
126F      NOPP
1270      NOPP
1271      NOPP
1272      JF0      RCV18      ;DELAY 7 CYCLES IN FAST MODE
1274      NOPP      ;DELAY 8 CYCLES IN SLOW MODE

1275      RCV15      NOPP
1275      NOPP
1276      NOPP
1277      NOPP
1278      NOPP
1279      JF0      RCV18      ;DELAY 6 CPU CYCLES IN FAST MODE
127B      NOPP
127C      NOPP
127D      NOPP
127E      NOPP
127F      NOPP
1280      NOPP
1281      NOPP
1282      NOPP
1283      NOPP
1284      NOPP
1285      NOPP
1286      NOPP
1287      NOPP
1288      NOPP      ;DELAY 20 CYCLES IN SLOW MODE

1289      RCV18      RRC    A          ;SHIFT OUT NEXT BIT TO COMPARE
128A      JC      RCV16      ;IF BIT IS A ONE
128C      JNSOD     RCV17      ;IF RECEIVED BIT IS ZERO
128E      RCV19      LNGJMP INVDF    ;GO PROCESS INVALID DATA FRAME
128E      RCV16      JNSOD     RCV19      ;IF RECEIVED BIT IS ZERO, ERROR
1291      RCV17      CLR    C
1293      JNZ      RCV15      ;IF DONE ALL BITS IN CHECKSUM
```

```
;      ACKNOWLEDGE THE DATA FRAME

1296      PAUSE  R0,US500
129A      PAUSE  R0,US500      ;DELAY 1000 US

129E      CLRSID
12A0      MOVI   A,ACK      ;SEND START BIT
12A2      CLR    C          ;NORMAL ACK
12A3      CPL    C
12A4      PAUSE  R0,1
12A5      RCV23
12A5      PAUSE  R0,2
12A7      JF0   RCV26      ;IF FAST MODE
12A9      PAUSE  R0,14

12AD      RCV26
12AD      RRC   A          ;SHIFT OUT NEXT BIT
12AE      JC    RCV24      ;IF BIT IS A ONE
12B0      CLRSID
12B2      JUMP  RCV25      ;SEND OUT A ZERO

12B4      RCV24
12B4      SETSID
12B6      JUMP  RCV25      ;SEND OUT A ONE
12B8      RCV25
12B8      CLR   C          ;EQUALIZE TIME AROUND BOTH PATHS
12B9      JNZ   RCV23      ;IF DONE WITH 8 BITS

;      RETURN TO CALLER

12BB      IN    A,P2
12BC      ANLI A,$FF-ACLR  ;GET ACTIVITY CODE
12BE      XRLI A,APOPT
12C0      JZ    RCV20      ;IF PUT OPTION TABLE
12C2      LNGJMP PUTRR    ;GO TO PUT RECEIVE RETURN
12C5      RCV20
12C5      LNGJMP POPTRR   ;GO TO PUT OPTION TABLE RECIEVE RETURN
```

12C8

```
**      SEND - SEND DATA FRAME
*
*      ENTRY CONDITIONS:
*          (NUMBER OF BYTES TO SEND)-1 IN R0 (0 IF NO DATA FRAME)
*          F1 SET IF ERROR, CLEAR IF SUCCESS
*
*      EXIT CONDITIONS:
*          ENTERS IDLE STATE
*

12C8 = 1300      ASSERT *<=$1300
                  ORG    $1300

1300      SEND
;
SEND COMPLT/ERROR

1300      MOV     A,PSW
1301      ORLI   A,1           ;INDICATE NO NEED TO UPDATE CSTAT
1303      MOV    PSW,A
1304      MOVI   A,ERROR
1306      JF1    SEND0         ;IF ERROR
1308      MOV    A,PSW
1309      ANLI   A,$FE
130B      MOV    PSW,A       ;INDICATE CSTAT UPDATE DESIRED
130C      MOVI   A,COMPLT
130E      SEND0
;
LOOP TO SEND ONE BYTE

130E      SEND1
CLRSID      ;SEND START BIT
1310      CLR    C
1311      CPL    C
1312      NOPP
1313      NOPP
1314      NOPP      ;DELAY 3 CYCLES
1315      SEND2
1315      NOPP
1316      NOPP
1317      JF0    SEND3      ;DELAY 4 CYCLES IN FAST MODE
1319      NOPP
131A      NOPP
131B      NOPP
131C      NOPP
131D      NOPP
131E      NOPP
131F      NOPP
1320      NOPP
1321      NOPP
1322      NOPP
1323      NOPP
1324      NOPP
1325      NOPP
1326      NOPP      ;DELAY 18 CYCLES IN SLOW MODE
```

```
1327      SEND3          RRC    A           ;SHIFT OUT NEXT BIT
1327      SEND3          JC     SEND4        ;IF BIT IS A ONE
1328      CLRSID         ;SEND OUT A ZERO
132A      JUMP           SEND5
132C      SEND4          SETSID         ;SEND OUT A ONE
132E      JUMP           SEND5        ;EQUALIZE TIME AROUND BOTH PATHS
1330      SEND5          CLR    C           ;IF NOT DONE WITH 8 BITS
1332      1332
1333      1333
1334      ;      CHECK TO SEE IF DATA FOLLOWS
1335      MOV   A,R0
1336      JZ    SEND7        ;IF NO DATA FOLLOWS
1338      PAUSE R0,US600
1339      PAUSE R0,US600        ;DELAY 1200 US, LEAVING R0 = 0
1340      XCH   A,R0        ;RESTORE R0, INIT CHECKSUM (IN A) TO 0
1341      CLR   F1           ;INDICATE LAST BYTE NOT SENT
1342      ;      SEND THE DATA FRAME
1343      SEND11         CLRSID         ;SEND START BIT
1344      ADD   A,XR0
1345      ADDCI A,0          ;UPDATE CHECKSUM
1346      XCH   A,XR0        ;SAVE CHECKSUM, BRING DATA BYTE TO A
1347      CLR   C
1348      CPL   C
1349      JFO  SEND16        ;IF FAST MODE
134A      JUMP           SEND10
134B      SEND12         NOPP
134C      NOPP
134D      JFO  SEND13        ;DELAY 4 CYCLES IN FAST MODE
134E      NOPP
134F      SEND10         NOPP
1350      NOPP
1351      NOPP
1352      NOPP
1353      NOPP
1354      NOPP
1355      NOPP
1356      NOPP
1357      NOPP
1358      NOPP
1359      NOPP
135A      NOPP
135B      NOPP
135C      NOPP
135D      NOPP
135E      NOPP
135F      SEND16         NOPP        ;DELAY 18 CYCLES IN SLOW MODE
135G      SEND13         RRC    A           ;SHIFT OUT NEXT BIT
135H      JC    SEND14        ;IF BIT IS A ONE
135I      CLRSID         ;SEND OUT A ZERO
1360      JUMP           SEND15
```

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 PERSEPHONE MINI/MICROFLOPPY DISK CONTROLLER D1:PERSEPH.ASM
 SERIAL DATA FRAME TRANSMITTER

```

1367      SEND14
1367      SETSID      ;SEND OUT A ONE
1369      JUMP   SEND15  ;EQUALIZE TIME AROUND BOTH PATHS
136B      SEND15
136B      CLR    C
136C      JNZ    SEND12 ;IF NOT DONE WITH 8 BITS

;       GET NEXT BYTE TO SEND

136E      DJNZ   R0,SEND6  ;ADVANCE POINTER
1370      JF1   SEND17  ;IF LAST BYTE HAS BEEN SENT
1372      MOV    A,T
1373      XCH   A,R1  ;GET LAST BYTE OF FRAME
1374      INCR  R0  ;BYTE TO RAM, CHECKSUM TO A
1375      CPL   F1  ;SO DJNZ WILL FAIL AGAIN
1376      JF0   SEND11 ;INDICATE LAST BYTE SENT
1378      JUMP  SEND18 ;IF FAST MODE

137A      SEND6
137A      INCR  R0
137B      MOV   A,XR0  ;BRING CHECKSUM TO A
137C      DECR  R0
137D      JF0   SEND11 ;IF FAST MODE
137F      NOPP
1380      NOPP
1381      NOPP
1382      NOPP
1383      NOPP

1384      SEND18
1384      NOPP
1385      NOPP
1386      NOPP
1387      NOPP
1388      NOPP
1389      NOPP
138A      NOPP      ;DELAY 12 CYCLES
138B      JUMP   SEND11 ;GO SEND THE BYTE

138D      SEND17
138D      MOV   A,R1  ;MOVE CHECKSUM TO A
138E      JF0   SEND1  ;IF FAST MODE
1390      NOPP
1391      NOPP
1392      NOPP
1393      NOPP
1394      NOPP
1395      NOPP
1396      NOPP
1397      NOPP
1398      NOPP
1399      NOPP
139A      NOPP      ;DELAY 12 CYCLES
139B      NOPP
139C      JUMP   SEND1  ;GO SEND THE CHECKSUM

;       UPDATE CSTAT IF NECESSARY, GO TO IDLE

```

```
139E      SEND7
139E      MOV     A,PSW
139F      JB0    SEND9      ;IF NO NEED TO UPDATE CSTAT
13A1      MOVI   R0,CSTAT
13A3      MOVI   XR0,0      ;UPDATE STATUS TO SUCCESS
13A5      SEND9
13A5      LNGJMP IDLE      ;GO TO IDLE STATE
```

13A8

** STAT - GET STATUS

| | | | |
|------|-------|----------------|-------------------------------|
| 13A8 | STAT | LNGCAL SENDAK | ;SEND ACKNOWLEDGE |
| 13AC | | PAUSE R0,US500 | |
| 13B0 | | PAUSE R0,US500 | ;1000 US COMPLT DELAY |
| 13B4 | | MOVI R3,0 | ;FOR SS/SD |
| 13B6 | | IN A,P1 | |
| 13B7 | | ANLI A,DDEN | |
| 13B9 | | JNZ STAT5 | ;IF FM |
| 13BB | | MOVI R3,\$80 | ;FOR SS/2D |
| 13BD | | IN A,P2 | |
| 13BE | | JB5 STAT5 | ;IF 128 BYTES/SECTOR |
| 13C0 | | MOVI R3,\$A0 | ;FOR DS/DD |
| 13C2 | | JB4 STAT5 | ;IF DS/DD |
| 13C4 | | MOVI R3,\$20 | |
| 13C6 | STAT5 | MOVI R0,CSTAT | |
| 13C6 | | MOV A,XR0 | ;GET CONTROLLER STATUS |
| 13C8 | | ORL A,R3 | |
| 13C9 | | MOV R3,A | |
| 13CA | | MOVI R2,\$FF | ;HARDWARE STATUS FOR NO ERROR |
| 13CB | | IN A,P1 | |
| 13CD | | ANLI A,MR | |
| 13CE | | JZ STAT1 | ;IF RESET IS LOW |
| 13D0 | | SETREG RSTA | |
| 13D2 | | MOVX A,XR0 | ;READ 1770 STATUS REGISTER |
| 13D6 | | CPL A | ;INVERT IT |
| 13D7 | | MOV R2,A | ;SAVE IT |
| 13D8 | | JB7 STAT1 | ;IF MOTOR OFF |
| 13D9 | | MOV A,R3 | |
| 13DB | | ORLI A,\$10 | ;TURN ON MOTOR BIT |
| 13DC | | MOV R3,A | |
| 13DE | | MOVI R1,\$78 | ;TIMEOUT |
| 13DF | STAT1 | MOVI A,0 | |
| 13E1 | | MOV T,A | ;LAST BYTE = 0 |
| 13E3 | | MOVI R0,3 | ;LENGTH OF FRAME -1 |
| 13E4 | | CLR F1 | ;SIGNAL NO ERROR |
| 13E6 | | LNGJMP SEND | ;SEND DATA FRAME |
| 13E7 | | | |

13EA

```
**      SPEED - SET SIO SPEED

13EA = 1400      ASSERT *<=$1400
                  ORG $1400

1400      SPEED      MOVI R0,CAUX1
1400          MOV A,XR0
1402          JZ  SPEED1      ;IF SLOW SPEED DESIRED
1403          XRLI A,1
1405          JNZ SPEED2      ;IF INVALID SPEED CODE

;      SET FAST SPEED
;      NOTE: INTERRUPTS MUST BE DISABLED AT THIS POINT

1409          CLR F0
140A          CPL F0
140B          JUMP SPEED3

;      SET SLOW SPEED

140D      SPEED1      CLR F0
140D          SPEED3      LNGCAL SENDAK      ;ACKNOWLEDGE
140E          PAUSE R0,US500
140E          PAUSE R0,US500      ;DELAY, LEAVING R0 = 0
1412          CLR F1      ;INDICATE NO ERROR
1416          LNGJMP SEND      ;SEND COMPLT, GO TO IDLE
141A
141B

;      PROCESS INVALID CODE

141E      SPEED2      LNGJMP INVCF      ;INVALID COMMAND FRAME
```

```

1421
**      GOPT - GET OPTION TABLE

1421      GOPT
1421      LNGCAL SENDAK      ;ACKNOWLEDGE
1425      PAUSE R0,US500
1429      PAUSE R0,US500      ;GENERATE COMPLT DELAY
142D      MOVI R0,11
142F      MOVI XR0,40      ;NUMBER OF TRACKS
1431      DECR R0
1432      MOVI XR0,SRATE    ;STEP RATE
1434      DECR R0
1435      MOVI XR0,0      ;SECTORS PER TRACK (MSB)
1437      DECR R0
1438      IN A,P2
1439      ANLI A,$FF-CFCLR  ;GET CURRENT CONFIG
143B      XRLI A,CFSS2D
143D      MOVI XR0,26      ;26 SECTORS PER TRACK FOR SS/2D
143F      JZ GOPT1        ;IF SS/2D
1441      MOVI XR0,18      ;18 SECTORS PER TRACK FOR OTHERS
1443      IN A,P2
1444      JB5 GOPT1        ;IF SS/SD
1446      DIS I
1447      ORLI P2,SECTSZ
1449      IN A,P2
144A      JB5 GOPT2        ;IF DRIVE IS A MINIFLOPPY
144C      MOVI XR0,16      ;16 SECTORS PER TRACK FOR MICROFLOPPY
144E      GOPT2
144E      ANLI P2,$FF-SECTSZ ;FIX UP SECTOR SIZE BIT
1450      EN I
1451      GOPT1
1451      DECR R0
1452      MOVI XR0,0      ;SINGLE SIDED
1454      IN A,P2
1455      ANLI A,$FF-CFCLR  ;GET CURRENT CONFIG
1457      XRLI A,CFDSDD
1459      JNZ GOPT3        ;IF NOT DS/DD
145B      MOVI XR0,1      ;DOUBLE SIDED
145D      GOPT3
145D      DECR R0
145E      MOVI XR0,0      ;FM
1460      IN A,P2
1461      ANLI A,$FF-CFCLR  ;GET CURRENT CONFIG
1463      XRLI A,CFSSD
1465      JNZ GOPT4        ;IF NOT SS/SD
1467      MOVI XR0,4      ;MFM
1469      GOPT4
1469      DECR R0
146A      MOVI XR0,0
146C      DECR R0
146D      MOVI XR0,$80      ;128 BYTES PER SECTOR
146F      IN A,P2
1470      JB5 GOPT5        ;IF 128 BYTES PER SECTOR
1472      INCR R0
1473      MOVI XR0,1
1475      DECR R0

```

```
1476      MOVI    XR0,0          ;256 BYTES PER SECTOR
1478      GOPTS5
1478      DECR    R0
1479      MOVI    XR0,1          ;DRIVE PRESENT
147B      DECR    R0
147C      MOVI    XR0,HSACK    ;FAST MODE
147E      JFO     GOPT6       ;IF FAST MODE
1480      MOVI    XR0,ACK       ;SLOW MODE
1482      GOPT6
1482      CLR     A
1483      MOV     T,A
1484      MOV     R1,A
1485      MOVI    R0,11         ;FRAME SIZE
1487      CLR     F1           ;NO ERROR
1488      LNGJMP  SEND         ;SEND FRAME, GO TO IDLE
```

148B

```
**      POPT - PUT OPTION TABLE

148B      POPT
148B          LNGCAL SENDAK      ;ACKNOWLEDGE
148F          MOVI   R0,11       ;FRAME SIZE
1491          LNGJMP RECV       ;GO RECEIVE THE FRAME
1494          POPTRR
1494          MOVI   R0,8        ;OFFSET TO # OF SECTORS PER TRACK
1496          DIS    I
1497          IN    A,P2
1498          ORLI  A,CFCLR     ;GET CURRENT CONFIG
149A          MOV    R1,A       ;SAVE IT
149B          ORLI  P2,$FF-CFCLR ;SET CONFIG TO ALL 1'S

;      CHECK FOR SS/SD MODE

149D          MOVI  R2,CFSSSD OR CFCLR
149F          MOV   A,R6        ;RECORDING MODE
14A0          JNZ   POPT1      ;IF NOT FM
14A2          MOV   A,R7        ;NUMBER OF SIDES
14A3          JNZ   POPTER     ;IF NOT SINGLE SIDED, ERROR
14A5          IN    A,P2
14A6          JB5   POPTSU     ;IF MINIFOLPPY, SUCCESS
14A8          JUMP  POPTER     ;ELSE, ERROR

;      CHECK RECORDING MODE FOR MFM

14AA      POPT1
14AA          XRLI  A,4
14AC          JNZ   POPTER     ;NOT MFM, ERROR

;      CHECK FOR DS/DD

14AE          MOVI  R2,CFDSD OR CFCLR
14B0          MOV   A,R7        ;NUMBER OF SIDES
14B1          JZ    POPT2      ;IF SINGLE SIDE
14B3          XRLI  A,1
14B5          JNZ   POPTER     ;NOT DOUBLE SIDED, ERROR
14B7          ORLI  P1,SS0      ;TRY TO SELECT SECOND SIDE
14B9          IN    A,P1
14BA          ANLI P1,$FF-SS0  ;RE-SELECT FIRST SIDE
14BC          ANLI A,SS0
14BE          JNZ   POPTSU     ;SECOND SIDE OK
14C0          JUMP  POPTER     ;ELSE ERROR

;      CHECK FOR SS/2D

14C2      POPT2
14C2          MOVI  R2,CFSS2D OR CFCLR
14C4          MOV   A,XR0      ;# OF SECTORS PER TRACK
14C5          XRLI  A,26
14C7          JNZ   POPT3      ;IF NOT SS/2D
14C9          MOV   A,R5        ;# BYTES PER SECTOR MSB
14CA          JNZ   POPT3      ;IF NOT SS/2D
14CC          MOV   A,R4        ;# BYTES PER SECTOR LSB
```

```
14CD      XRLI    A,$80
14CF      JNZ     POPT3      ;IF NOT SS/2D
14D1      IN      A,P2
14D2      JB5     POPTSU    ;IN DRIVE IS A MINIFLOPPY
14D4      JUMP   POPTER    ;IF MICROFLOPPY, ERROR

;      COME HERE FOR SS/DD

14D6      POPT3      MOVI    R2,CFSSDD OR CFCLR
;      COME HERE FOR SUCCESSFUL CONFIGURE

14D8      POPTSU    MOV     A,R2      ;NEW CONFIGURATION
14D8      MOV     R1,A
14D9      CLR     F1      ;NO ERROR
14DA      JUMP   POPT4
;      COME HERE IF ERROR

14DD      POPTER    CLR     F1
14DE      CPL     F1      ;ERROR FLAG
14DF      MOVI   R0,CSTAT
14E1      MOVI   XR0,$04      ;STATUS FOR UNSUCCESSFUL OPERATION

;      SEND COMPLT/ERROR AND GO TO IDLE

14E3      POPT4      IN      A,P2
14E3      ANL     A,R1      ;SET NEW CONFIG
14E4      ORLI   A,INP2    ;SET INPUT BITS
14E5      OUTL   P2,A      ;WRITE TO PORT
14E7      EN      I
14E8      PAUSE  R0,US500   ;DELAY, LEAVING R0 = 0 (NO DATA FRAME)
14E9      LNGJMP SEND      ;SEND COMPLT/ERROR, GO TO IDLE
14ED
```

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 FORMAT ROUTINES

```

14F0          **      FMT - FORMAT IN CURRENT DENSITY
14F0 = 1500   ASSERT *<=$1500
              ORG $1500

1500          FMT      ORLI P1,DDEN      ;SELECT FM
1500          IN A,P2
1502          ANLI A,$FF-CFCLR ;GET CURRENT CONFIG
1503          XRLI A,CFSSSD
1505          JZ FMT1       ;IF SS/SD

              **      FMTD - FORMAT IN DUAL DENSITY
1509          FMTD     ANLI P1,$FF-DDEN ;SELECT MFM

              ;      SEND ACKNOWLEDGE
150B          FMT1     LNGCAL SENDAK
150B          ;      DO RESET SEQUENCE
150F          ANLI P2,$FF-HKNOWN ;INDICATE HEAD POSITION UNKNOWN
1511          ANLI P1,$FF-MR   ;SEND RESET TO 1770
1513          PAUSE R0,US500
1517          ORLI P1,MR      ;REMOVE RESET
1519          PAUSE R0,US500
151D          SETREG WCMD
1521          MOVI A,FRCINT
1523          MOVX XR0,A      ;INITIATE FORCED INTERRUPT
1524          PAUSE R0,US200

              ;      INITIALIZE DATA FRAMES FOR ERROR
1528          IN A,P2
1529          RL A
152A          RL A
152B          ANLI A,$80
152D          DECR A      ;OFFSET TO FIRST BYTE OF DATA FRAME
152E          MOV R3,A      ;SAVE IT
152F          MOV R0,A
1530          CLR A
1531          MOV XR0,A
1532          DECR R0
1533          MOV XR0,A
1534          CPL A
1535          DECR R0
1536          MOV XR0,A
1537          DECR R0
1538          MOV XR0,A
1539          MOVI R0,CSTAT
153B          MOVI XR0,$04      ;STATUS FOR UNSUCCESSFUL OPERATION

```

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 FORMAT ROUTINES

```

;      SET FLAG TO INDICATE FORMAT
153D      CLR   F1
;
;      RESTORE TO TRACK 0
153E      FMT2
153E      ANLI  P2,$FF-HKNOWN ;INDICATE HEAD POSITION UNKNOWN
1540      SETREG WCMD
1544      MOVI   A,REST
1546      MOVX   XR0,A      ;SEND RESTORE COMMAND TO 1770
1547      MOVI   R0,SEC3   ;TRIP COUNT FOR 3-SECOND DELAY
1549      CLR    A
154A      MOV    T,A      ;RESET TIMER
154B      STRT   T
154C      FMT3
154C      JTF   FMT4
154E      FMT5
154E      IN    A,P1
154F      ANLI  A,INTRQ
1551      JZ    FMT3      ;IF NOT DONE
1553      STOP   TCNT
1554      SETREG RSTA
1558      MOVX   A,XR0      ;READ STATUS TO CLEAR INTRQ
1559      SETREG WTRK
155D      CLR    A
155E      MOVX   XR0,A      ;UPDATE TRACK REG TO 0
155F      MOV    R2,A      ;INIT R2 = TRACK
1560      ANLI  P1,$FF-SS0
1562      PAUSE  R0,US500
1566      JUMP   FMT6      ;GO TO TRACK LOOP
1568      FMT4
1568      DJNZ   R0,FMT5   ;IF NOT TIMED OUT
;
;      PROCESS ERROR
156A      FMT7
156A      STOP   TCNT
156B      SETREG WCMD
156F      MOVI   A,FRCINT
1571      MOVX   XR0,A      ;DO FORCED INTERRUPT
1572      PAUSE  R0,US200
1576      CLR    F1
1577      CPL    F1      ;INDICATE ERROR
1578      MOV    A,R3
1579      MOV    R0,A      ;DATA FRAME LENGTH
157A      LNGJMP SEND      ;SEND ERROR, GO TO IDLE
;
;      MAIN TRACK LOOP
;      SEEK DESIRED TRACK
157D      FMT6
157D      SETREG WDAT

```

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 FORMAT ROUTINES

```

1581      MOV     A,R2          ;GET DESIRED TRACK
1582      MOVX   XR0,A         ;WRITE IT TO DATA REG
1583      ANLI   P2,$FF-HKNOWN ;INDICATE HEAD POSITION UNKNOWN
1585      SETREG WCMD
1589      MOVI   A,SEEK
158B      MOVX   XR0,A         ;ISSUE SEEK COMMAND
158C      CLR    A
158D      MOV    T,A
158E      JTF    FMT8         ;CLEAR TIMER OVERFLOW FLAG
1590      FMT8   MOVI   R0,SEC1 ;TRIP COUNT FOR 1-SECOND TIMEOUT
1592      FMT9   JTF   FMT10
1592      FMT11  IN    A,P1
1594      ANLI   A,INTRQ
1595      JZ    FMT9         ;IF NOT DONE
1597
1599      STOP   TCNT
159A      SETREG RSTA
159E      MOVX   XR0,A         ;READ STATUS REG TO CLEAR INTRQ
159F      JUMP   ILV          ;GO CONSTRUCT INTERLEAVE TABLE

15A1      FMT10  DJNZ   R0,FMT11 ;IF NOT TIMED OUT
15A1      15A3   JUMP   FMT7      ;GO PROCESS ERROR
15A5      ILV
15A5      ;      SET R4 = NUMBER OF SECTORS PER TRACK
15A5      ;      R5 = -(SECTOR INTERLEAVE FACTOR)
15A5      ;      R1 = INIT INDEX INTO INTERLEAVE TABLE
15A5      MOVI   R4,18          ;18 SECTORS PER TRACK
15A7      MOVI   R5,$100-9       ;SECTOR INTERLEAVE FACTOR OF 9
15A9      IN    A,P2
15AA      JB5   ILV1         ;IF 128 BYTES/SECTOR
15AC      JF0   ILV2         ;IF FAST MODE
15AE      MOVI   R5,$100-15      ;SECTOR INTERLEAVE OF 15
15B0      ILV2   DIS   I
15B1      ORLI   P2,SECTSZ
15B3      IN    A,P2
15B4      JB5   ILV3         ;IF MINIFLOPPY
15B6      MOVI   R4,16          ;16 SECTORS/TRACK FOR MICROFLOPPY
15B8      ILV3   ANLI  P2,$FF-SECTSZ
15BA      EN    I
15BB      JUMP   ILV4
15BD      ILV1   IN    A,P1
15BE      JB3   ILV4         ;IF FM
15C0      MOVI   R4,26          ;26 SECTORS/TRACK
15C2      MOVI   R5,$100-13      ;SECTOR INTERLEAVE OF 13

```

```

;      CLEAR THE INTERLEAVE TABLE

15C4      ILV4      MOV     A,R4
15C4      MOV     R0,A      ;INIT R0 = NUMBER OF SECTORS
15C5      ADDI    A,$7F
15C6      MOV     R6,A      ;SAVE INIT INDEX INTO TABLE
15C8      MOV     R1,A
15C9
15CA      ILV5      MOVI    XR1,0      ;STORE 0 IN TABLE
15CA      DECR    R1      ;ADVANCE POINTER
15CC      MOV     A,R1
15CD      JB7     ILV5      ;IF NOT DONE WITH TABLE

;      FILL THE TABLE

15D0      MOV     A,R6
15D1      JUMP   ILV7
15D3      ILV6      MOV     A,R1      ;TABLE INDEX
15D3      ADD     A,R5      ;ADD INTERLEAVE FACTOR
15D4      ILV8      JB7     ILV7      ;IF STILL WITHIN RANGE
15D5      ADD     A,R4      ;WRAP POINTER
15D7      ILV7      MOV     R1,A
15D8      MOV     A,XR1
15D9      JZ      ILV9      ;IF TABLE ENTRY NOT YET USED
15DA      DECR    R1
15DC      MOV     A,R1
15DD      JUMP   ILV8      ;USE NEXT ENTRY
15DE      ILV9      IN      A,P1
15E0      ANLI    A,SS0
15E1      JNZ     ILV10     ;IF SECOND SIDE
15E3      MOV     A,R0
15E5      CPL     A
15E6      ADD     A,R4
15E7      ADDI   A,2      ;REFLECT SECTOR NUMBER
15E8      JUMP   ILV11
15EA      ILV10     MOV     A,R0
15EC      ILV11     MOV     XR1,A      ;STORE SECTOR NUMBER IN TABLE
15ED      DJNZ    R0,ILV6      ;IF MORE SECTORS TO DO
15EE      MOV     A,R6
15F0      MOV     R1,A      ;R1 = INIT INDEX INTO TABLE
15F1

;      INITIALIZE FOR WRITE TRACK

15F2      JUMP   WTR
15F4 = 1600 ASSERT *<=$1600
15F4      ORG    $1600

1600      WTR      JF1     VFY      ;IF VERIFY

```

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 FORMAT ROUTINES

```

;      SET R4 = GAP FILLER
;      R5 = PRE-MARK GAP LENGTH
;      R6 = POST-ID GAP LENGTH
;      R7 = POST-DATA GAP LENGTH
;      R0 = POST-INDEX GAP LENGTH - 1

1602      MOVI   R4,$00
1604      MOVI   R5,6
1606      MOVI   R6,11
1608      MOVI   R7,12
160A      MOVI   R0,39
160C      IN     A,P1
160D      JB3    WTR1      ;IF FM
160F      MOVI   R4,$4E
1611      MOVI   R5,12
1613      MOVI   R6,22
1615      MOVI   R7,24
1617      MOVI   R0,59

;      ISSUE WRITE TRACK COMMAND

1619      WTR1
1619      SETREG WCMD
161D      MOVI   A,WRTRK
161F      MOVX   XR0,A
1620      SETREG WDAT
1624      CLR    A
1625      MOV    T,A      ;RESET THE TIMER
1626      JTF    WTR2      ;CLEAR TIMER OVERFLOW FLAG
1628      WTR2
1628      MOVI   A,SEC1      ;TRIP COUNT FOR 1 SECOND TIMEOUT
162A      XCH    A,R4
162B      STRT   T
162C      JUMP   WTR5      ;GO WRITE THE TRACK

**      VERIFY TRACK

162E      VFY
162E      ;      ISSUE READ SECTOR COMMAND

162E      VFY1
162E      STOP   TCNT
162F      CLR    A
1630      MOV    T,A
1631      MOV    A,R3
1632      INCR   A
1633      MOV    R0,A      ;SECTOR SIZE
1634      MOVI   R4,SEC1      ;TRIP COUNT FOR 1 SECOND TIMEOUT
1636      SETREG WTRK
163A      MOV    A,R2      ;TRACK NUMBER
163B      MOVX   XR0,A
163C      SETREG WSEC
1640      MOV    A,XR1      ;SECTOR NUMBER FROM INTERLEAVE TABLE
1641      DECR   R1
1642      MOVX   XR0,A      ;ADVANCE INTERLEAVE POINTER

```

```
1643      SETREG WCMD
1647      MOVI A, RDSEC
1649      MOVX XR0, A
164A      SETREG RDAT
164E      STRT T

;      READ THE DATA BYTES

164F      VFY2
164F      JTF VFY3
1651      VFY4
1651      JNDRQ VFY2
1653      JNDRQ VFY2
1655      VFY5
1655      MOVX A, XR0
1656      DJNZ R0, VFY4      ;IF MORE BYTE TO READ

;      WAIT FOR OPERATION COMPLETE

1658      CLR A
1659      MOV T,A          ;RESET THE TIMER
165A      JTF VFY6          ;RESET TIMER OVERFLOW FLAG
165C      VFY6
165C      JTF VFY7          ;IF TIMED OUT
165E      IN A,P1
165F      ANLI A,INTRQ
1661      JZ VFY6          ;IF NOT DONE

;      READ STATUS

1663      STOP TCNT
1664      SETREG RSTA
1668      MOVX A, XR0      ;READ STATUS REG
1669      ANLI A,$3C      ;RELEVANT STATUS BITS
166B      JNZ VFY7          ;IF ERROR

;      SEE IF MORE SECTORS TO DO

166D      MOV A,R1
166E      JB7 VFY1          ;IF MORE SECTORS
1670      JUMP FMT12        ;GO DO NEXT TRACK

;      HANDLE VERIFY TIMEOUTS

1672      VFY3
1672      JNDRQ VFY8
1674      JDRQ VFY5
1676      VFY8
1676      DJNZ R4, VFY4      ;IF NOT TIMED OUT
1678      VFY7
1678      JUMP FMT7          ;GO HANDLE ERROR

**      GO TO NEXT TRACK

167A      FMT12
167A      IN A,P1
167B      JB6 FMT13        ;IF SECOND SIDE
```

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 FORMAT ROUTINES

```

167D      INCR   R2          ;NEXT TRACK
167E      MOV    A,R2
167F      XRLI   A,40
1681      JNZ    FMT14      ;IF NOT DONE WITH 40 TRACKS
1683      IN     A,P2
1684      ANLI   A,$FF-CFCLR
1686      XRLI   A,CFDSDD
1688      JNZ    FMT15      ;IF NOT DOUBLE SIDED
168A      ORLI   P1,SSO     ;SELECT SECOND SIDE
168C      PAUSE   R0,US500

1690      FMT13
1690      MOV    A,R2
1691      JZ     FMT15      ;IF DONE WITH 40 TRACKS
1693      DECR   R2          ;NEXT TRACK
1694      FMT14
1694      JUMP   FMT6       ;GO DO NEW TRACK

;      COME HERE IF COMPLETE PASS IS FINISHED

1696      FMT15
1696      JF1    FMT16      ;IF WE JUST FINISHED VERIFY
1698      CPL    F1          ;INDICATE VERIFY IN PROGRESS
1699      JUMP   FMT2       ;GO DO SECOND PASS

;      COME HERE FOR SUCCESSFUL FORMAT/VERIFY

169B      FMT16
169B      STOP   TCNT
169C      CLR    F1          ;INDICATE SUCCESS
169D      MOV    A,R3
169E      MOV    R0,A        ;DATA FRAME LENGTH
169F      MOVI   XR0,$FF
16A1      DECR   R0
16A2      MOVI   XR0,$FF      ;INDICATE NO BAD SECTORS
16A4      INCR   R0
16A5      LNGJMP SEND        ;SEND COMPLT AND FRAME, GO TO IDLE

**      WRITE TRACK

16A8 = 1700      ASSERT *<=$1700
16A8 = 1700      ORG    $1700

;      WRITE POST-INDEX GAP (GAP I)

1700      WTR3
1700      JTF    WTR4
1702      WTR5
1702      JNDRQ  WTR3
1704      JNDRQ  WTR3      ;FILTER DRQ GLITCHES
1706      WTR50
1706      MOVX   XR0,A        ;WRITE A GAP BYTE
1707      DJNZ   R0,WTR5      ;IF NOT DONE WITH GAP
1709      MOV    T,A          ;RESET THE TIMER
170A      JTF    WTR9      ;RESET TIMER OVERFLOW FLAG
170C      WTR9
170C      JDRQ   WTR10

```

```
170E      WTR11
170E      JTF      WTR12
1710      JNDRQ   WTR11
1712
1712      WTR10
1712      MOVX     XR0,A          ;WRITE LAST BYTE OF GAP
1713      MOV       R4,A
;
;      SECTOR LOOP

1714      WTR6
;
;      WRITE PRE-IDAM GAP (END OF GAP III)

1714      MOV       A,R5
1715      MOV       R0,A
1716      CLR       A
1717      JDRQ    WTR44
1719      WTR8
1719      JTF      WTR12
171B      WTR13
171B      JNDRQ   WTR8
171D      WTR44
171D      MOVX     XR0,A
171E      DJNZ    R0,WTR13
;
;      WRITE MFM SYNC MARKS

1720      IN       A,P1
1721      JB3     WTR14          ;IF FM
1723      MOVI    A,$F5          ;F5 WRITES MFM SYNC MARK
1725      JDRQ    WTR15
1727      WTR16
1727      JTF      WTR12
1729      JNDRQ   WTR16
172B      WTR15
172B      MOVX     XR0,A
172C      MOVI    R0,2           ;WRITE 2 MORE SYNC MARKS
172E      WTR17
172E      JTF      WTR12
1730      WTR18
1730      JNDRQ   WTR17
1732      MOVX     XR0,A
1733      DJNZ    R0,WTR18
;
;      WRITE ID FIELD

1735      WTR14
1735      MOVI    A,$FE          ;ID ADDRESS MARK (IDAM)
1737      JDRQ    WTR19
1739      WTR20
1739      JTF      WTR12
173B      JNDRQ   WTR20
173D      WTR19
173D      MOVX     XR0,A          ;WRITE IDAM
173E      WTR21
173E      MOV     A,R2           ;TRACK NUMBER
```

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 FORMAT ROUTINES

```

173F          JTF    WTR12
1741          JNDRQ  WTR21
1743          MOVX   XR0,A      ;WRITE TRACK NUMBER

1744          IN     A,P1
1745          RL     A
1746          RL     A
1747          ANLI   A,1      ;SIDE NUMBER
1749          WTR22
1749          JTF    WTR12
174B          JNDRQ  WTR22
174D          MOVX   XR0,A      ;WRITE SIDE NUMBER

174E          WTR23
174F          MOV    A,XR1      ;SECTOR NUMBER FROM INTERLEAVE TABLE
174F          DECR   R1        ;ADVANCE INTERLEAVE POINTER
1750          WTR23
1750          JTF    WTR12
1752          JNDRQ  WTR23
1754          MOVX   XR0,A      ;WRITE SECTOR NUMBER

1755          WTR24
1756          IN     A,P2      ;IF SECTOR SIZE IS 128
1756          JB5   WTR24
1758          INCR   R0
1759          WTR24
1759          MOV    A,R0      ;SECTOR SIZE CODE
175A          WTR25
175A          JTF    WTR12
175C          JNDRQ  WTR25
175E          MOVX   XR0,A      ;WRITE SECTOR SIZE CODE

175F          WTR26
1761          MOVI   A,$F7      ;F7 WRITES CRC
1761          JTF    WTR12
1763          JNDRQ  WTR26
1765          MOVX   XR0,A      ;WRITE CRC

;       WRITE POST-ID GAP (START OF GAP II)

1766          WTR27
1767          MOV    A,R6      ;LENGTH OF POST-ID GAP
1768          MOV    R0,A      ;GAP FILLER
1769          WTR27
1769          JTF    WTR12
176B          WTR28
176B          JNDRQ  WTR27
176D          MOVX   XR0,A
176E          DJNZ   R0,WTR28

;       WRITE PRE-DAM GAP (END OF GAP II)

1770          WTR29
1771          MOV    A,R5
1771          MOV    R0,A
1772          CLR    A
1773          MOV    T,A      ;RESET THE TIMER
1774          WTR29
1774          JTF    WTR12
1776          WTR30

```

```
1776      JNDRQ  WTR29
1778      MOVX   XR0,A
1779      DJNZ   R0,WTR30

;      WRITE MFM SYNC MARKS

177B      IN     A,P1
177C      JB3   WTR35      ;IF FM
177E      MOVI   A,$F5      ;F5 WRITES MFM SYNC MARK
1780      JDRQ   WTR32
1782      WTR31
1782      JTF    WTR12
1784      JNDRQ  WTR31
1786      WTR32
1786      MOVX   XR0,A
1787      MOVI   R0,2      ;WRITE 2 MORE SYNC MARKS
1789      WTR33
1789      JTF    WTR12
1788      WTR34
1788      JNDRQ  WTR33
178D      MOVX   XR0,A
178E      DJNZ   R0,WTR34

;      WRITE DATA FIELD

1790      WTR35
1790      MOVI   A,$FB      ;FB IS DATA ADDRESS MARK (DAM)
1792      JDRQ   WTR37
1794      WTR36
1794      JTF    WTR12
1796      JNDRQ  WTR36
1798      WTR37
1798      MOVX   XR0,A      ;WRITE DAM

1799      WTR39
179A      MOV    A,R3
179B      MOV    R0,A
179C      INCR   R0
179C      MOVI   A,$FF      ;SECTOR SIZE
179E      JNDRQ  WTR39
179E      JTF    WTR12
17A0      WTR40
17A0      JNDRQ  WTR39
17A2      MOVX   XR0,A      ;WRITE DATA BYTE
17A3      DJNZ   R0,WTR40      ;IF MORE DATA

17A5      WTR41
17A7      MOVI   A,$F7      ;F7 WRITES CRC
17A7      JTF    WTR12
17A9      JNDRQ  WTR41
17AB      MOVX   XR0,A      ;WRITE CRC

;      WRITE POST-DATA GAP (START OF GAP III)

17AC      WTR42
17AD      MOV    A,R7      ;LENGTH OF POST-DATA GAP
17AE      MOV    R0,A
17AE      MOV    A,R4      ;GAP FILLER BYTE
```

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 PERSEPHONE MINI/MICROFLOPPY DISK CONTROLLER D1:PERSEPH.ASM
 FORMAT ROUTINES

```

17AF          JTF      WTR12
17B1          WTR43   JNDRQ   WTR42
17B1          MOVX    XR0,A      ;WRITE A GAP BYTE
17B3          DJNZ    R0,WTR43
17B4

;       SEE IF MORE SECTORS TO WRITE

17B6          MOV     A,R1
17B7          JB7    WTR6      ;IF MORE SECTORS

;       WRITE GAP IV

17B9          WTR45   MOVI    R0,SEC1    ;TRIP COUNT FOR 1 SECOND TIMEOUT
17BB          MOV     A,R4      ;GAP FILLER BYTE
17BC          JNDRQ   WTR46
17BE          MOVX    XR0,A      ;WRITE GAP BYTE
17BF          WTR46   IN      A,P1
17C0          JB2    WTR47      ;IF DONE
17C2          MOV     A,R4
17C3          JNDRQ   WTR48
17C5          MOVX    XR0,A      ;WRITE GAP BYTE
17C6          WTR48   JTF     WTR49
17C6          JUMP   WTR45
17C8          WTR49   DJNZ    R0,WTR45    ;IF NOT TIMED OUT
17CA

;       HANDLE TIMEOUT

17CC          WTR12   JUMP   FMT7
17CC

17CE          WTR4    JNDRQ   WTR51
17CE          JDRQ    WTR50      ;FILTER DRQ GLITCHES
17D0          WTR51   DJNZ    R4,WTR5
17D2          IN      A,P1      ;IF NOT TIMED OUT
17D4          CPL    A
17D5          JB2    WTR52      ;IF OPERATION NOT COMPLETE
17D6          SETREG  RSTA
17D8          MOVX    A,XR0      ;READ STATUS
17DC          CPL    A
17DD          JB6    WTR52      ;IF NOT WRITE PROTECT
17DE          MOVI    R0,CSTAT
17E0          MOVI    XR0,$0C      ;STATUS FOR WRITE PROTECT
17E2          WTR52   JUMP   FMT7
17E4

;       HANDLE WRITE TRACK OPERATION COMPLETE

17E6          WTR47   SETREG  RSTA
17E6          MOVX    A,XR0      ;READ STATUS
17EA

```

```
17EB      ANL I    A,$44      ;RELEVANT STATUS BITS
17ED      JNZ      WTR52      ;IF ERROR
17EF      JUMP     FMT12      ;GO TO NEXT TRACK
```

17F1

```
**      CTS - CALCULATE TRACK AND SECTOR
*
*      ENTRY CONDITIONS:
*          LOGICAL SECTOR NUMBER IN CAUX1 AND CAUX2
*          PSW[1:0] = RETURN TARGET (CTSRT0 - CTSRT2)
*
*      EXIT CONDITIONS:
*          PHYSICAL TRACK NUMBER IN 1770 DATA REG
*          PHYSICAL SECTOR NUMBER IN 1770 SECTOR REG
*          A MODIFIED
*          R0-R7 UNMODIFIED
*          C SET IF ERROR
*          C CLEAR IF SUCCESS
*
17F1 = 1800      ASSERT *<=$17FD
                  ORG   $1800
1800      CTS
;
;      SAVE REGISTERS WE WILL USE
1800      MOV    A,R0
1801      MOVI   R0,R0SAV
1803      MOV    XR0,A
1804      DECR   R0
1805      MOV    A,R1
1806      MOV    XR0,A
1807      DECR   R0
1808      MOV    A,R2
1809      MOV    XR0,A
180A      DECR   R0
180B      MOV    A,R3
180C      MOV    XR0,A
180D      DECR   R0
180E      MOV    A,R4
180F      MOV    XR0,A
1810      DECR   R0
1811      MOV    A,R5
1812      MOV    XR0,A
;
;      CHECK FOR COPY PROTECT COMMAND
1813      MOVI   R0,CCOMND
1815      MOV    A,XR0
1816      DECR   R0
1817      XRLI   A,$72
1819      JNZ    CTS10      ;IF NOT COPY PROTECT COMMAND
181B      MOV    A,XR0      ;BRING IN TRACK #
181C      MOV    R0,A
181D      ADDI   A,$FF-39
181F      JC     CTSERR    ;IF TRACK NUMBER TOO BIG
1821      ANLI   P1,$FF-SS0  ;SELECT FIRST SIDE
1823      MOVI   A,IMPSEC   ;'IMPOSSIBLE' SECTOR NUMBER
1825      JUMP   CTS11
```

```
;      BRING REDUCED LOGICAL SECTOR NUMBER INTO R2 (LSB) AND R3 (MSB)

1827      CTS10
1827      MOV     A,XR0
1828      ADDI    A,$FF
182A      MOV     R2,A
182B      DECR    R0
182C      MOV     A,XR0
182D      ADDCI   A,$FF
182F      MOV     R3,A

;      SET R1 = NEGATIVE OF NUMBER OF SECTORS PER TRACK
;      R4,R5 = NEGATIVE OF NUMBER OF SECTORS PER SIDE (LSB,MSB)

1830      MOVI    R1,$100-18
1832      MOVI    R4,LOW [0-720]
1834      MOVI    R5,HIGH [0-720]
1836      IN      A,P2
1837      JB5    CTS1           ;IF 128 BYTES PER SECTOR
1839      DIS    I
183A      ORLI   P2,SECTSZ        ;TRY TO SET 128 BYTES PER SECTOR
183C      IN      A,P2
183D      JB5    CTS2           ;IF DRIVE IS A MINIFLOPPY
183F      MOVI    R1,$100-16        ;16 SECTORS PER TRACK FOR MICROFLOPPY
1841      MOVI    R4,LOW [0-640]
1843      MOVI    R5,LOW [0-640]

1845      CTS2
1845      ANLI   P2,$FF-SECTSZ
1847      EN     I
1848      JUMP   CTS3
184A      CTS1
184A      IN      A,P1
184B      ANLI   A,DDEN
184D      JNZ    CTS3           ;IF SINGLE DENSITY
184F      MOVI    R1,$100-26        ;26 SECTORS PER TRACK FOR DUAL DENSITY
1851      MOVI    R4,LOW [0-1040]
1853      MOVI    R5,HIGH [0-1040]

;      DO BOUNDS CHECK, UPDATE SIDE SELECT OUTPUT

1855      CTS3
1855      MOV     A,R2
1856      ADD     A,R4
1857      MOV     R0,A
1858      MOV     A,R3
1859      ADDC   A,R5
185A      JNC    CTS4           ;IF IN BOUNDS ON FIRST SIDE
185C      XCH    A,R0
185D      ADD     A,R4
185E      CPL    A
185F      MOV     R2,A
1860      MOV     A,R0
1861      ADDC   A,R5
1862      CPL    A
1863      MOV     R3,A
1864      JC     CTSERR         ;IF OUT OF BOUNDS ON SECOND SIDE
```

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 PERSEPHONE MINI/MICROFLOPPY DISK CONTROLLER D1:PERSEPH.ASM
 TRACK/SECTOR CALCULATION

```

1866      IN     A,P2
1867      ANLI   A,$FF-CFCLR
1869      XRLI   A,CFDSDD
186B      CLR    C
186C      CPL    C           ;INDICATE ERROR
186D      JNZ    CTSERR      ;IF SINGLE SIDED

186F      ORLI   P1,SS0      ;SELECT SECOND SIDE
1871      JUMP   CTS5

1873      CTS4
1873      ANLI   P1,$FF-SS0    ;SELECT FIRST SIDE
;
;          CALCULATE TRACK AND SECTOR

1875      CTS5
1875      MOVI   R0,$FF      ;INIT TO TRACK 0
1877      MOV    A,R2        ;SECTOR NUMBER LSB
1878      INCR   R3
1879      CTS6
1879      INCR   R0          ;COUNT THE TRACK
187A      ADD    A,R1        ;SUBTRACT NUMBER OF SECTORS PER TRACK
187B      JC    CTS6        ;IF NO BORROW
187D      DJNZ   R3,CTS6    ;DECREMENT MSB
187F      XCH    A,R1
1880      CPL    A
1881      INCR   A
1882      ADD    A,R1        ;ADD BACK NUMBER OF SECTORS
1883      INCR   A          ;ADD 1 FOR PHYSICAL SECTOR #

;
;          STORE TRACK AND SECTOR INTO 1770

1884      CTS11
1884      SETREG WSEC
1888      MOVX   XR0,A        ;WRITE SECTOR # INTO SECTOR REG
1889      SETREG WDAT
188D      MOV    A,R0
188E      MOVX   XR0,A        ;WRITE TRACK # INTO DATA REG
188F      CLR    C          ;INDICATE SUCCESS
;
;          RESTORE SAVED REGISTERS

1890      CTSERR
1890      MOVI   R0,R5SAV
1892      MOV    A,XR0
1893      MOV    R5,A
1894      INCR   R0
1895      MOV    A,XR0
1896      MOV    R4,A
1897      INCR   R0
1898      MOV    A,XR0
1899      MOV    R3,A
189A      INCR   R0
189B      MOV    A,XR0
189C      MOV    R2,A
189D      INCR   R0
189E      MOV    A,XR0

```

```
189F      MOV    R1,A
18A0      INCR   R0
18A1      MOV    A,XR0
18A2      MOV    R0,A
;
;       RETURN TO CALLER
18A3      MOV    A,PSW
18A4      JB0   CTS8
18A6      JB1   CTS7
18A8      LNGJMP CTSRT0
18AB      CTS7
18AB      LNGJMP CTSRT2
18AE      CTS8
18AE      LNGJMP CTSRT1
```

18B1

```
**      GET - GET SECTOR
**      PUT - PUT SECTOR
**      PUTV - PUT SECTOR WITH VERIFY

18B1 = 1900      ASSERT *<=$1900
                  ORG    $1900

1900      GET
1900      PUT
1900      PUTV

;      RAISE 1770 RESET IF IT IS LOW

1900      IN     A,P1
1901      ANLI   A,MR
1903      JNZ    SECT0      ;IF RESET IS HIGH
1905      ORLI   P1,MR      ;RAISE RESET
1907      PAUSE   R6,US500    ;DELAY 500 US
1908      SECT0
190B      SETREG WCMD
190F      MOVI    A,FRCINT
1911      MOVX    XR0,A      ;INITIATE FORCED INTERRUPT
1912      PAUSE   R6,US200    ;DELAY 200 US

;      CALCULATE TRACK AND SECTOR NUMBERS

1916      MOV    A,PSW
1917      ANLI   A,$FC
1919      MOV    PSW,A      ;SELECT RETURN TARGET = CTSRT0
191A      LNGJMP CTS
191D      CTSRT0
191D      JNC    SECT1      ;IF SUCCESS
191F      IN     A,P2
1920      CPL    A
1921      JB5    SECT2      ;IF SECTOR SIZE = 256
1923      IN     A,P1
1924      ANLI   A,DDEN
1926      JZ     SECT2      ;IF MFM
1928      ANLI   P1,$FF-DDEN ;SET TO MFM
192A      MOV    A,PSW
192B      ANLI   A,$FC
192D      ORLI   A,1
192F      MOV    PSW,A      ;SELECT RETURN TARGET = CTSRT1
1930      LNGJMP CTS      ;TRY AGAIN TO CALCULATE
1933      CTSRT1
1933      JNC    SECT1      ;IF SUCCESS
1935      ORLI   P1,DDEN    ;RETURN SETTING TO FM
1937      SECT2
1937      LNGJMP INVCF     ;INVALID COMMAND FRAME

;      SEND ACKNOWLEDGE

193A      SECT1
193A      LNGCAL SENDAK
```

```

;      IN CASE OF PUT, RECEIVE DATA FRAME

193E      IN     A,P2
193F      ANLI   A,$FF-ACLR
1941      XRLI   A,AGET
1943      JZ     SECT3      ;IF GET

1945      MOVI   R0,$7F      ;FOR 128-BYTE SECTOR
1947      MOV    A,PSW
1948      ORLI   A,1
194A      MOV    PSW,A      ;SIGNAL NO BUFFER EXPANSION
194B      IN     A,P2
194C      JB5    SECT4      ;IF SECTOR SIZE IS 128 BYTES
194E      IN     A,P1
194F      ANLI   A,SS0
1951      JNZ    SEC5      ;IF SECOND SIDE
1953      SETREG RDAT
1957      MOVX   A,XR0
1958      JNZ    SEC5      ;IF NOT TRACK 0
195A      SETREG RSEC
195E      MOVX   A,XR0
195F      ADDI   A,$FC
1961      JC    SEC5      ;IF NOT SECTOR 1, 2, OR 3
1963      MOV    A,PSW
1964      ANLI   A,$FE      ;INDICATE BUFFER EXPANSION
1966      MOV    PSW,A
1967      JUMP   SECT4
1969      SEC5
1969      MOVI   R0,$FF      ;FOR 256-BYTE SECTORS
196B      SECT4
196B      LNGJMP RECV      ;GO RECEIVE DATA FRAME
196E      PUTRR
196E      MOV    A,PSW
196F      JB0    SECT3      ;IF NO BUFFER EXPANSION
1971      MOVI   R0,$80
1973      MOV    A,T      ;LAST BYTE OF FRAME
1974      MOV    XR0,A      ;STORE IT IN HIGH RAM
1975      DECR   R0
1976      SEC6
1976      MOV    A,XR0      ;GET A BYTE OF THE DATA FRAME
1977      XCH    A,R0
1978      ORLI   A,$80
197A      XCH    A,R0
197B      MOV    XR0,A      ;STORE IT INTO HIGH RAM
197C      XCH    A,R0
197D      ANLI   A,$7F
197F      XCH    A,R0
1980      DJNZ   R0,SEC6      ;IF DONE WITH 128 BYTES

;      CHECK TO SEE IF HEAD POSITION IS KNOWN

1982      SECT3
1982      CLR    F1      ;INIT HARD RETRY FLAG
1983      IN     A,P2
1984      ANLI   A,HKNOWN
1986      JZ     SEC19      ;IF HEAD UNKNOWN, DO RESTORE SEQUENCE
1988      JUMP   SEC20      ;DO SEEK

```

198A SEC19
198A SETREG RDAT

** RST - RESTORE SEQUENCE
*
* ENTRY CONDITIONS:
* P1 SET UP TO READ REG CONTAINING DESIRED TRACK
* LAST BYTE OF DATA FRAME IN TIMER

198E RST
; READ IN DESIRED TRACK AND SECTOR

198E MOVX A,XR0 ;GET DESIRED TRACK
198F MOV R0,A
1990 MOV A,PSW
1991 XRL A,R0
1992 ANLI A,\$F8
1994 XRL A,R0
1995 MOV PSW,A ;STORE BITS 2-0 OF TRACK IN PSW
1996 MOV A,R0
1997 RL A
1998 RL A
1999 MOV R0,A
199A SETREG RSEC
199E MOVX A,XR0 ;GET DESIRED SECTOR
199F XRLI A,IMPSEC
19A1 JZ RST2 ;IF 'IMPOSSIBLE' SECTOR
19A3 XRLI A,IMPSEC

19A5 RST2
XRL A,R0
19A6 ANLI A,\$1F
19A8 XRL A,R0 ;COMBINE TRACK[5:3] WITH SECTOR[4:0]

; DO HARD RESET TO THE 1770

19A9 ANLI P2,\$FF-HKNOWN ;INDICATE HEAD POSITION UNKNOWN
19AB ANLI P1,\$FF-MR ;LOWER RESET
19AD PAUSE R0,US500 ;500 US DELAY
19B1 ORLI P1,MR ;RAISE RESET
19B3 PAUSE R0,US500 ;500 US DELAY
19B7 MOV R0,A
19B8 MOVI A,FRCINT
19BA MOVX XR0,A ;DO FORCED INTERRUPT
19BB MOV A,R0
19BC PAUSE R0,US200 ;200 US DELAY

; WRITE SECTOR NUMBER INTO SECTOR REG

19C0 MOV R0,A
19C1 ANLI A,\$1F
19C3 JNZ RST1
19C5 MOVI A,IMPSEC ;'IMPOSSIBLE' SECTOR

19C7 RST1
SETREG WSEC
MOVX XR0,A

```
; ISSUE RESTORE COMMAND

19CC      MOVI   A,REST
19CE      SETREG WCMD
19D2      MOVX   XR0,A

; SET UP COUNTER AND TIMER FOR RESTORE 3-SECOND TIMEOUT

19D3      MOV    A,T          ;LAST DATA BYTE
19D4      XCH    A,R0          ;PUT DATA BYTE IN R0
19D5      RR     A
19D6      RR     A
19D7      RR     A
19D8      RR     A
19D9      RR     A          ;MOVE TRACK[5:3] INTO BITS 2-0
19DA      ANLI   A,$07          ;INIT 5-BIT COUNTER

; DELAY APPROXIMATELY 100 MS

19DC      JUMP   RST3
19DE = 1A00 ASSERT *<=$1A00
           ORG    $1A00

1A00      RST3
1A00      MOV    T,A          ;INIT TIMER
1A01      STRT   T
1A02      RST4
1A02      JTF    RST5
1A04      JUMP   RST4
1A06      RST5
1A06      JTF    RST6
1A08      JUMP   RST5
1A0A      RST6
1A0A      JTF    RST7
1A0C      JUMP   RST6
1A0E      RST7
1A0E      JTF    RST8
1A10      JUMP   RST7
1A12      RST8
1A12      JTF    RST9
1A14      JUMP   RST8
1A16      RST9
1A16      JTF    RST10
1A18      JUMP   RST9
1A1A      RST10
1A1A      JTF    RST11
1A1C      JUMP   RST10
1A1E      RST11
1A1E      STOP   TCNT

; SEE IF RESTORE COMMAND IS DONE

1A1F      MOV    T,A
1A20      IN     A,P1
1A21      JB2    RST12          ;IF RESTORE IS DONE
1A23      MOV    A,T
```

```

1A24      ADDI   A,$98
1A26      JNC    RST3          ;IF TIME NOT EXPIRED
1A28      RL    A
1A29      RL    A
1A2A      RL    A
1A2B      ANLI  A,$38
1A2D      XCH   A,R0
1A2E      MOV    T,A          ;PUT LAST DATA BYTE IN TIMER
1A2F      MOVI   A,FRCINT
1A31      SETREG WCMD
1A35      MOVX   XR0,A        ;INITIATE FORCED INTERRUPT
1A36      MOV    A,PSW
1A37      XRL   A,R0
1A38      ANLI  A,$07
1A3A      XRL   A,R0          ;RECONSTRUCT TRACK NUMBER
1A3B      PAUSE  R0,US200     ;DELAY 200 US
1A3F      SETREG WTRK
1A43      MOVX   XR0,A        ;WRITE DESIRED TRACK INTO TRACK REG
1A44      JUMP   HRT          ;GO DO HARD RETRY

; COME HERE IF RESTORE COMPLETE
; AT THIS POINT, LAST DATA BYTE IS IN R0

1A46      RST12
1A46      SETREG RSTA
1A4A      MOVX   A,XR0          ;READ STATUS REG TO CLEAR INTRQ
1A4B      IN    A,P2
1A4C      CPL   A
1A4D      JB5    RST13          ;IF SS/DD OR DS/DD

; FOR SS/SD AND SS/2D, DO READ ADDRESS TO DETERMINE DENSITY

1A4F      ANLI  P1,$FF-DDEN   ;SELECT MFM
1A51      MOV    A,R0          ;LAST BYTE TO A
1A52      PAUSE  R0,US500     ;DELAY 500 US
1A56      MOV    R0,A          ;LAST BYTE TO R0
1A57      MOVI   A,RDADR
1A59      SETREG WCMD
1A5D      MOVX   XR0,A        ;ISSUE READ ADDRESS COMMAND
1A5E      CLR    A
1A5F      MOV    T,A          ;INIT TIMER
1A60      MOVI   A,MS240      ;TRIP COUNT FOR 240 MS DELAY
1A62      JTF    RST16          ;CLEAR TIMER OVERFLOW FLAG
1A64      RST16
1A64      STRT   T
1A65      SETREG RDAT          ;PREPARE TO READ DATA REG

1A69      RST17
1A69      JTF    RST18
1A6B      RST34
1A6B      JNDRQ  RST17
1A6D      JNDRQ  RST17          ;FILTER DRQ GLITCHES

; READ SIX BYTES FROM THE 1770

1A6F      RST19
1A6F      MOVX   A,XR0          ;READ FIRST BYTE

```

```

1A70      CLR   A
1A71      MOV   T,A
1A72      JTF   RST20      ;INIT TIMER
1A74      RST20
1A74      JDRQ  RST21
1A76      RST22
1A76      JTF   RST25
1A78      JNDRQ RST22
1A7A      RST21
1A7A      MOVX  A,XR0      ;READ SECOND BYTE
1A7B      RST23
1A7B      JTF   RST25
1A7D      JNDRQ RST23
1A7F      MOVX  A,XR0      ;READ THIRD BYTE
1A80      RST24
1A80      JTF   RST25
1A82      JNDRQ RST24
1A84      MOVX  A,XR0      ;READ FOURTH BYTE
1A85      RST29
1A85      JTF   RST25
1A87      JNDRQ RST29
1A89      MOVX  A,XR0      ;READ FIFTH BYTE
1A8A      RST30
1A8A      JTF   RST25
1A8C      JNDRQ RST30
1A8E      MOVX  A,XR0      ;READ SIXTH BYTE
1A8F      RST31
1A8F      JTF   RST25
1A91      IN    A,P1
1A92      CPL   A
1A93      JB2   RST31      ;IF 1770 STILL BUSY
1A95      SETREG RSTA
1A99      MOVX  A,XR0      ;READ STATUS REG
1A9A      ANLI  A,$1C      ;RELEVANT STATUS BITS FOR READ ADDRESS
1A9C      JNZ   RST25      ;IF READ ADDRESS FAILED
1A9E      JUMP  RST26      ;IF READ ADDRESS IS SUCCESSFUL
;
;      HANDLE TIMER TRIPS WHILE WAITING FOR FIRST BYTE
1AA0      RST18
1AA0      JNDRQ RST32
1AA2      JDRQ  RST19      ;FILTER DRQ GLITCHES
1AA4      RST32
1AA4      DECR   A
1AA5      JNDRQ RST33
1AA7      JDRQ  RST19      ;FILTER DRQ GLITCHES
1AA9      RST33
1AA9      JNZ   RST34      ;IF NOT TIMED OUT
;
;      COME HERE IF READ ADDRESS FAILS
;      AT THIS POINT, LAST DATA BYTE IS IN R0
1AAB      RST25
1AAB      MOVI   A,FRCINT
1AAD      SETREG WCMD

```

```

1AB1      MOVX   XR0,A          ;DO FORCED INTERRUPT
1AB2      MOV    A,R0
1AB3      PAUSE  R0,US200       ;DELAY 200 US
1AB7      ORLI   P1,DDEN        ;SELECT FM
1AB9      PAUSE  R0,US500       ;DELAY 500 US
1ABD      MOV    R0,A

; FINISH UP READ ADDRESS
; AT THIS POINT, LAST DATA BYTE IN R0

1ABE      RST26
1ABE      STOP   TCNT
1ABF      MOV    A,R0
1AC0      MOV    T,A          ;LAST DATA BYTE TO TIMER
1AC1      MOV    A,PSW
1AC2      ANLI   A,$FC
1AC4      ORLI   A,2
1AC6      MOV    PSW,A         ;SELECT RETRUN TARGET = CTSRT2
1AC7      LNGJMP CTS          ;CALCULATE TRACK AND SECTOR
1ACA      CTSRT2
1ACA      JNC    RST35        ;IF SUCCESS
1ACC      CLR    F1
1ACD      CPL    F1          ;FORCE HARD RETRY TO FAIL
1ACE      JUMP   HRT          ;GO DO HARD RETRY

; RECONSTRUCT TRACK NUMBER

1AD0      RST13
1AD0      MOV    A,T
1AD1      RL    A
1AD2      RL    A
1AD3      RL    A
1AD4      ANLI   A,$38
1AD6      XCH    A,R0
1AD7      MOV    T,A          ;PUT LAST DATA BYTE INTO TIMER
1AD8      MOV    A,PSW
1AD9      XRL    A,R0
1ADA      ANLI   A,$07
1ADC      XRL    A,R0          ;RECONSTRUCT TRACK NUMBER
1ADD      SETREG WDAT
1AE1      MOVX   XR0,A         ;WRITE DESIRED TRACK INTO DATA REG
1AE2      RST35
1AE2      CLR    A
1AE3      SETREG WTRK
1AE7      MOVX   XR0,A         ;UPDATE TRACK REG TO ZERO

; END OF RESTORE SEQUENCE

; ISSUE SEEK COMMAND
; AT THIS POINT, LAST DATA BYTE IS IN TIMER

1AE8      SEC7
1AE8      JUMP   SEC20
1AE8      ASSERT *=<=$1B00
1AEA = 1B00  ORG    $1B00

; CHECK TO SEE IF ALREADY AT CORRECT TRACK

```

```

1B00      SEC20
1B00      SETREG RTRK
1B04      MOVX A,XR0      ;READ CURRENT TRACK
1B05      MOV R0,A
1B06      SETREG RDAT
1B0A      MOVX A,XR0      ;READ DESIRED TRACK
1B08      XRL A,R0      ;COMPARE
1B0C      JNZ SEC21      ;IF NOT AT CORRECT TRACK
1B0E      MOV A,T
1B0F      MOV R0,A      ;PUT LAST DATA BYTE IN R0
1B10      JUMP SEC22      ;GO FINISH SEEK
1B12
1B12      SEC21
1B12      ANLI P2,$FF-HKNOWN ;INDICATE HEAD POSITION UNKNOWN
1B14      MOVI A,SEEK
1B16      SETREG WCMD
1B1A      MOVX XR0,A      ;ISSUE SEEK COMMAND
1B1B      MOV A,T      ;FETCH LAST DATA BYTE
1B1C      MOV R0,A      ;STORE IT
1B1D      CLR A
1B1E      MOV T,A      ;INIT TIMER
1B1F      MOV A,PSW
1B20      ANLI A,$3F
1B22      ORLI A,$07      ;INIT 5-BIT COUNTER WITHIN PSW
1B24      STRT T

;      WAIT FOR SEEK COMMAND TO BE COMPLETE

1B25      SEC8
1B25      MOV PSW,A
1B26      SEC10
1B26      JTF SEC11
1B28      IN A,P1
1B29      JB2 SEC9      ;IF SEEK DONE
1B2B      JUMP SEC10
1B2D      SEC11
1B2D      JTF SEC12
1B2F      IN A,P1
1B30      JB2 SEC9      ;IF SEEK DONE
1B32      JUMP SEC11
1B34      SEC12
1B34      JTF SEC13
1B36      IN A,P1
1B37      JB2 SEC9      ;IF SEEK DONE
1B39      JUMP SEC12
1B3B      SEC13
1B3B      JTF SEC14
1B3D      IN A,P1
1B3E      JB2 SEC9      ;IF SEEK DONE
1B40      JUMP SEC13
1B42      SEC14
1B42      JTF SEC15
1B44      IN A,P1
1B45      JB2 SEC9      ;IF SEEK DONE
1B47      JUMP SEC14
1B49      SEC15
1B49      JTF SEC16

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```

1B4B      IN     A,P1
1B4C      JB2    SEC9          ;IF SEEK DONE
1B4E      JUMP   SEC15

;      HANDLE POSSIBLE SEEK TIMEOUT

1B50      SEC16
1B50      MOV    A,PSW
1B51      DECR   A
1B52      JB3    SEC8          ;IF NOT TIMED OUT
1B54      ADDI   A,$48
1B56      JNC    SEC8          ;IF NOT TIMED OUT
1B58      STOP   TCNT
1B59      MOV    A,R0
1B5A      MOV    T,A          ;PUT LAST DATA BYTE IN TIMER
1B5B      MOVI   A,FRCINT
1B5D      SETREG WCMD
1B61      MOVX   XR0,A        ;DO FORCED INTERRUPT
1B62      PAUSE   R0,US200    ;DELAY 200 US
1B66      SETREG RDAT
1B6A      MOVX   A,XR0         ;READ IN TARGET TRACK
1B6B      SETREG WTRK
1B6F      MOVX   XR0,A        ;WRITE IT INTO TRACK REG
1B70      JUMP   HRT          ;GO DO HARD RETRY

;      COME HERE FOR SUCCESSFUL SEEK
;      AT THIS POINT, LAST DATA BYTE IN R0

1B72      SEC9
1B72      SETREG RSTA
1B76      MOVX   A,XR0         ;READ STATUS REG TO CLEAR INTRQ
1B77      SEC22
1B77      ORLI   P2,HKNOWN    ;INDICATE HEAD POSITION KNOWN
1B79      MOV    A,PSW
1B7A      ANLI   A,$F8
1B7C      ORLI   A,2

;      COME HERE TO EXECUTE SOFT RETRY

1B7E      JUMP   SEC18
1B7E      ASSERT *=<=$1C00
1B80 = 1C00 ORG    $1C00

1C00      SEC18
1C00      MOV    PSW,A        ;INIT SOFT RETRY COUNTER
1C01      STOP   TCNT
1C02      SEC17
1C02      JTF    SEC17        ;CLEAR TIMER OVERFLOW FLAG
1C04      SEC17
1C04      CLR    A
1C05      MOV    T,A          ;INIT TIMER FOR ID FIELD TIMEOUT

**      HANDLE GET COMMAND

1C06      IN     A,P2
1C07      ANLI   A,$FF-ACLR
1C09      XRLI   A,AGET

```

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 SECTOR I/O

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1C0B          JZ      GET1           ;IF A GET COMMAND
1C0D          JUMP   PUT1

;       INITIALIZATION FOR GET

1C0F          GET1
1C0F          IN     A,P2
1C10          MOVI   R1,$7F        ;INIT INDEX FOR 128-BYTE SECTORS
1C12          JB5    GET2           ;IF SECTOR SIZE IS 128
1C14          MOVI   R1,$FF        ;INIT INDEX FOR 256-BYTE SECTORS
1C16          GET2
1C16          MOV    A,R1
1C17          MOV    R0,A
1C18          DECR   R0             ;INDEX FOR SECOND BYTE
1C19          MOVI   R2,MS2300     ;TRIP COUNT FOR 2.3 SECOND DELAY

;       ISSUE READ SECTOR COMMAND

1C1B          SETREG WCMD
1C1F          MOVI   A,RDSEC
1C21          MOVX   XR0,A

;       READ FIRST DATA BYTE

1C22          SETREG RDAT
1C26          GET3
1C26          JTF   GET4
1C28          GET6
1C28          JNDRQ GET3          ;WAIT FOR DRQ
1C2A          JNDRQ GET3          ;FILTER DRQ GLITCHES
1C2C          GET5
1C2C          MOVX   A,XR0          ;BRING IN FIRST BYTE
1C2D          CPL    A              ;COMPLEMENT IT
1C2E          MOV    XR1,A          ;STORE IT IN RAM
1C2F          CLR    A
1C30          MOV    T,A            ;RESET THE TIMER
1C31          JTF   GET18          ;RESET TIMER OVERFLOW FLAG
1C33          GET18
1C33          JDRQ  GET19

;       READ IN THE MIDDLE BYTES

1C35          GET8
1C35          JTF   GET9
1C37          GET7
1C37          JNDRQ GET8
1C39          GET19
1C39          MOVX   A,XR0          ;READ DATA BYTE
1C3A          CPL    A              ;COMPLEMENT IT
1C3B          MOV    XR0,A          ;STORE IT IN RAM
1C3C          DJNZ   R0,GET7        ;IF MORE BYTES TO DO

;       READ IN THE LAST BYTE

1C3E          GET10
1C3E          JTF   GET9
1C40          JNDRQ GET10

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```

1C42      MOVX   A,XR0      ;BRING IN LAST BYTE
1C43      CPL    A          ;COMPLEMENT IT
1C44      MOV    R0,A       ;STORE IT IN R0

;      WAIT FOR OPERATION COMPLETE

1C45      GET11
1C45      JTF    GET9
1C47      IN     A,P1
1C48      ANLI   A,INTRQ
1C4A      JZ    GET11      ;IF NOT COMPLETE
1C4C      STOP   TCNT
1C4D      MOV    A,R0
1C4E      MOV    T,A       ;PUT LAST BYTE IN TIMER
1C4F      SETREG RSTA
1C53      MOVX   A,XR0
1C54      MOV    R0,A       ;STORE OPERATION STATUS IN R0

;      RECOGNIZE MFM, TRACK 0, SIDE 0, SECTOR 1-3

1C55      IN     A,P1
1C56      ANLI   A,SS0 OR DDEN
1C58      JNZ    GET12      ;IF FM OR SIDE 1
1C5A      SETREG RTRK
1C5E      MOVX   A,XR0
1C5F      JNZ    GET12      ;IF NOT TRACK 0
1C61      SETREG RSEC
1C65      MOVX   A,XR0
1C66      ADDI   A,$FC
1C68      JC    GET12      ;IF NOT SECTOR 1, 2, OR 3

1C6A      IN     A,P2
1C6B      JB5   GET13      ;IF SS/SD OR SS/2D

1C6D      MOV    A,R0
1C6E      MOV    T,A       ;STORE STATUS IN TIMER
1C6F      MOVI   R0,$7F

1C71      GET14
1C71      MOV    A,R0
1C72      ORLI   A,$80
1C74      MOV    R0,A       ;POINT TO HIGH RAM
1C75      MOV    A,XR0      ;FETCH A BYTE FROM HIGH RAM
1C76      XCH    A,R0
1C77      ANLI   A,$7F
1C79      XCH    A,R0
1C7A      MOV    XR0,A      ;WRITE IT TO LOW RAM
1C7B      DJNZ   R0,GET14      ;IF MORE BYTES TO COPY
1C7D      MOVI   R0,$80
1C7F      MOV    A,XR0      ;NEW LAST BYTE
1C80      MOV    R0,A
1C81      MOV    A,T
1C82      XCH    A,R0      ;PUT STATUS IN R0
1C83      MOV    T,A       ;PUT LAST BYTE IN TIMER
1C84      MOVI   A,$7F      ;TRANSMIT POINTER
1C86      JUMP   GET15

1C88      GET13

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```
1C88      MOV    A,R0
1C89      ANLI   A,$FB          ;TURN OFF LOST DATA BIT
1C8B      MOV    R0,A

;     INITIALIZE R0 FOR TRANSMISSION

1C8C      GET12
1C8C      IN     A,P2
1C8D      RL    A
1C8E      RL    A
1C8F      ANLI   A,$80
1C91      DECR   A
1C92      GET15
1C92      XCH    A,R0          ;STATUS TO ACCUMULATOR

;     CHECK STATUS

1C93      ANLI   A,$3C          ;MASK RELEVANT BITS
1C95      JNZ    SRT           ;IF ERROR, GO DO SOFT RETRY

;     SUCCESSFUL COMPLETION OF GET

1C97      GET17
1C97      CLR    F1            ;INDICATE SUCCESS
1C98      LNGJMP SEND          ;SEND DATA FRAME, GO TO IDLE

;     HANDLE GET TIMEOUTS

1C9B      GET4
1C9B      JNDRQ  GET16
1C9D      JDRQ   GET5          ;FILTER DRQ GLITCHES
1C9F      GET16
1C9F      DJNZ   R2,GET6        ;IF TIME NOT EXHAUSTED
1CA1      STOP   TCNT
1CA2      SETREG WCMD
1CA6      MOVI   A,FRCINT
1CA8      MOVX   XR0,A          ;DO FORCED INTERRUPT
1CA9      PAUSE   R0,US200       ;DELAY 200 US
1CAD      JUMP   HRT           ;DO HARD RETRY

1CAF      GET9
1CAF      STOP   TCNT
1CB0      SETREG WCMD
1CB4      MOVI   A,FRCINT
1CB6      MOVX   XR0,A          ;DO FORCED INTERRUPT
1CB7      PAUSE   R0,US200

**      SRT - SOFT RETRY
*
*      ENTRY CONDITIONS:
*          LAST DATA BYTE IN TIMER

1CBB      SRT
1CBB      MOV    A,T
1CBC      MOV    R0,A          ;COPY LAST DATA BYTE INTO R0
1CBD      MOV    A,PSW
```

```
1CBE      DECR    A
1CBF      JB3     SEC18      ;IF RETRIES NOT EXHAUSTED

**      HRT - HARD RETRY
*
*      ENTRY CONDITIONS:
*          LAST DATA BYTE IN TIMER

1CC1      HRT
1CC1      JF1     HRT1      ;IF RETRIES EXHAUSTED
1CC3      CPL     F1       ;INDICATE RETRY IN PROGRESS
1CC4      SETREG  RTRK
1CC8      JUMP    RST      ;GO DO RESTORE SEQUENCE

1CCA      HRT1
1CCC      MOVI    R0,CSTAT
1CCC      MOVI    XR0,4      ;STATUS CODE FOR UNSUCCESSFUL OPERATION
1CCE      MOVI    R0,0      ;NO DATA FRAME
1CD0      IN      A,P2
1CD1      ANLI    A,$FF-ACLR
1CD3      XRLI    A,AGET
1CD5      JNZ     HRT2      ;IF PUT
1CD7      IN      A,P2
1CD8      RL      A
1CD9      RL      A
1CDA      ANLI    A,$80
1CDC      DECR    A
1CDD      MOV     R0,A      ;DATA FRAME LENGTH
1CDE      LNGJMP  SEND      ;SEND ERROR, GO TO IDLE

**      HANDLE PUT COMMAND
*
*      ENTRY CONDITIONS:
*          LAST DATA BYTE IN R0

1CE1 = 1D00 ASSERT *<=$1D00
                ORG    $1D00

1D00      PUT1
;
;      INITIALIZE FOR PUT

1D00      IN      A,P2
1D01      RL      A
1D02      RL      A
1D03      ANLI    A,$80
1D05      DECR    A
1D06      XCH     A,R0
1D07      XCH     A,XR0
1D08      CPL     A      ;COMPLEMENT FIRST BYTE
1D09      MOV     R0,A

;
;      ISSUE WRITE SECTOR COMMAND
```

```
1D0A      SETREG  WCMD
1D0E      MOVI    A,WRSEC
1D10      MOVX    XR0,A
1D11      SETREG  WDAT

;     SEND FIRST DATA BYTE

1D15      MOV     A,R0
1D16      MOVI    R0,MS2300 ;TRIP COUNT FOR 2.3 SECOND TIMEOUT
1D18      STRT    T

1D19      PUT2
1D19      JTF    PUT3
1D1B      PUT4
1D1B      JNDRQ  PUT2
1D1D      JNDRQ  PUT2      ;FILTER DRQ GLITCHES
1D1F      PUT5
1D1F      MOVX   XR0,A      ;WRITE FIRST BYTE
1D20      CPL    A          ;UN-COMPLEMENT
1D21      XCH    A,R0
1D22      CLR    A
1D23      MOV    T,A      ;RESET THE TIMER
1D24      JTF    PUT6      ;CLEAR TIMER OVERFLOW FLAG
1D26      PUT6
1D26      IN     A,P2
1D27      RL     A
1D28      RL     A
1D29      ANLI  A,$80
1D2B      DECR  A
1D2C      XCH   A,R0
1D2D      XCH   A,XR0      ;LAST BYTE TO ACCUMULATOR
1D2E      DECR  R0

;     WRITE THE MIDDLE BYTES

1D2F      PUT7
1D2F      XCH   A,XR0      ;GET A BYTE FROM RAM
1D30      CPL   A          ;COMPLEMENT IT
1D31      JDRQ  PUT13
1D33      PUT8
1D33      JTF   PUT9      ;IF TIMED OUT
1D35      JNDRQ  PUT8
1D37      PUT13
1D37      MOVX  XR0,A      ;WRITE THE BYTE
1D38      CPL   A          ;UN-COMPLEMENT IT
1D39      XCH   A,XR0      ;PUT IT BACK INTO RAM
1D3A      DJNZ  R0,PUT7      ;ADVANCE POINTER

;     WRITE THE LAST BYTE

1D3C      PUT10
1D3D      MOV   R0,A      ;SAVE LAST BYTE IN R0
1D3E      CPL   A          ;COMPLEMENT IT
1D3E      JDRQ  PUT14
1D40      PUT10
1D40      JTF   PUT11
1D42      JNDRQ  PUT10
1D44      PUT14
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```

1D44      MOVX   XR0,A          ;WRITE THE LAST BYTE
;
; WAIT FOR OPERATION COMPLETE

1D45      PUT12
1D45      JTF    PUT11
1D47      IN     A,P1
1D48      ANLI   A,INTRQ
1D4A      JZ    PUT12          ;IF NOT COMPLETE
1D4C      STOP   TCNT
1D4D      MOV    A,R0
1D4E      MOV    T,A          ;PUT LAST BYTE IN TIMER
1D4F      SETREG RSTA
1D53      MOVX   A,XR0          ;READ STATUS REG
1D54      JB6    PUT18          ;IF WRITE PROTECT
1D56      ANLI   A,$14          ;RELEVANT STATUS BITS
1D58      JZ    PTV             ;IF SUCCESS, GO DO VERIFY
1D5A      JUMP   SRT             ;FAILURE, GO DO SOFT RETRY

;
; HANDLE PUT TIMEOUTS

1D5C      PUT3
1D5C      JNDRQ  PUT16
1D5E      JDRQ   PUT5
1D60      PUT16
1D60      DJNZ   R0,PUT4          ;IF TIME NOT EXHAUSTED
1D62      STOP   TCNT
1D63      CPL    A              ;UN-COMPLEMENT
1D64      MOV    R0,A
1D65      IN     A,P2
1D66      RL    A
1D67      RL    A
1D68      ANLI   A,$80
1D6A      DECR   A
1D6B      XCH    A,R0
1D6C      XCH    A,XR0          ;RESTORE FIRST BYTE TO RAM
1D6D      MOV    T,A          ;LAST BYTE TO TIMER
1D6E      IN     A,P1
1D6F      ANLI   A,INTRQ
1D71      JZ    PUT17          ;IF OPERATION NOT COMPLETE
1D73      SETREG RSTA
1D77      MOVX   A,XR0          ;READ STATUS REG
1D78      JB6    PUT18          ;IF WRITE PROTECT
1D7A      PUT17
1D7A      SETREG WCMD
1D7E      MOVI   A,FRCINT
1D80      MOVX   XR0,A          ;DO FORCED INTERRUPT
1D81      PAUSE   R0,US200
1D85      JUMP   HRT             ;GO DO HARD RETRY

1D87      PUT9
1D87      CPL    A
1D88      XCH    A,XR0          ;PUT BYTE BACK IN RAM
1D89      MOV    R0,A          ;SAVE LAST BYTE IN R0
1D8A      PUT11
1D8A      STOP   TCNT
1D8B      MOV    A,R0

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1D8C      MOV   T,A          ;PUT LAST BYTE IN TIMER
1D8D      IN    A,P1
1D8E      ANLI A,INTRQ
1D90      JZ    PUT19        ;IF OPERATION NOT COMPLETE
1D92      SETREG RSTA
1D96      MOVX A,XR0         ;READ STATUS
1D97      JB6   PUT18        ;IF WRITE PROTECT
1D99      PUT19
1D99      SETREG WCMD
1D9D      MOVI A,FRCINT
1D9F      MOVX XR0,A         ;DO FORCED INTERRUPT
1DA0      PAUSE R0,US200     ;DELAY 200 US
1DA4      JUMP SRT          ;GO DO SOFT RETRY

1DA6      PUT18
1DA6      MOVI R0,CSTAT
1DA8      MOVI XR0,$0C       ;STATUS CODE FOR WRITE PROTECT
1DAA      MOVI R0,0          ;NO DATA FRAME
1DAC      CLR   F1
1DAD      CPL   F1          ;INDICATE ERROR
1DAE      LNGJMP SEND        ;SEND ERROR, GO TO IDLE

**      HANDLE VERIFICATION
*
*
*      ENTRY CONDITIONS:
*          LAST DATA BYTE IN TIMER

1DB1      PTV
1DB1      JUMP PTV1
1DB3 = 1E00 ASSERT *<=$1E00
1DB3 = 1E00 ORG $1E00

1E00      PTV1
1E00      IN    A,P2
1E01      ANLI A,$FF-ACLR
1E03      XRLI A,APUTV
1E05      JNZ   PTV10        ;IF VERIFY NOT REQUIRED

;      SHIFT AND COMPLEMENT INTERNAL RAM

1E07      IN    A,P2
1E08      RL    A
1E09      RL    A
1E0A      ANLI A,$80
1E0C      MOV   R0,A          ;INDEX TO FIRST DATA BYTE
1E0D      DECR R0
1E0E      RLC   A          ;SET CARRY FOR LATER USE
1E0F      MOV   A,T          ;LAST DATA BYTE TO ACCUMULATOR
1E10      CPL   A          ;COMPLEMENT IT
1E11      XCH   A,XR0         ;FIRST DATA BYTE TO ACCUMULATOR
1E12      CPL   A          ;COMPLEMENT IT
1E13      DECR R0
1E14      PTV11
1E14      XCH   A,XR0        ;BRING A DATA BYTE TO ACCUMULATOR
1E15      CPL   A          ;COMPLEMENT IT
1E16      INCR R0
1E17      XCH   A,XR0        ;SHIFT IT FORWARD ONE POSITION

```

```

1E18      DECR   R0
1E19      XCH    A,XR0      ;RESTORE FIRST DATA BYTE TO ACCUMULATOR
1E1A      DJNZ   R0,PTV11   ;IF MORE BYTES TO DO
1E1C      MOV    R0,A      ;PUT FIRST DATA BYTE IN R0

; ISSUE READ SECTOR COMMAND

1E1D      STOP   TCNT
1E1E      JTF    PTV12      ;CLEAR TIMER OVERFLOW FLAG
1E20      PTV12
1E20      CLR    A
1E21      MOV    T,A      ;RESET THE TIMER
1E22      SETREG WCMD
1E26      MOVI   A,RDSEC
1E28      MOVX   XR0,A
1E29      SETREG RDAT
1E2D      STRT   T
1E2E      MOVI   A,SEC1      ;TRIP COUNT FOR 1 SECOND TIMEOUT

; READ THE FIRST TWO BYTES

1E30      PTV2
1E30      JTF    PTV3
1E32      PTV4
1E32      JNDRQ PTV2
1E34      JNDRQ PTV2      ;FILTER DRQ GLITCHES
1E36      PTV13
1E36      MOVX   A,XR0      ;READ FIRST BYTE
1E37      XRL    A,R0      ;COMPARE
1E38      JNZ    PTV5      ;IF INCORRECT
1E3A      MOV    R0,A      ;STORE ZERO IN R0

1E3B      PTV6
1E3D      PTV7
1E3D      INCR   A
1E3E      JDRQ   PTV6
1E40      JZ     PTV5      ;IF TIMED OUT
1E42      JNDRQ PTV7

1E44      PTV6
1E44      MOVX   A,XR0      ;READ SECOND BYTE
1E45      XCH    A,R0
1E46      RRC    A
1E47      DECR   A      ;INDEX TO SECOND BYTE
1E48      XCH    A,R0
1E49      XRL    A,XR0      ;COMPARE
1E4A      JNZ    PTV5      ;IF INCORRECT
1E4C      DECR   R0

; READ AND COMPARE THE REMAINING BYTES

1E4D      PTV14
1E4D      JDRQ   PTV15
1E4F      PTV16
1E4F      INCR   A
1E50      JDRQ   PTV15
1E52      JZ     PTV5      ;IF TIMED OUT
1E54      JNDRQ PTV16

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```
1E56      PTV15      MOVX    A,XR0      ;READ BYTE
1E56      XRL     A,XR0      ;COMPARE
1E58      JNZ     PTV5      ;IF INCORRECT
1E5A      DJNZ    R0,PTV14   ;IF MORE BYTES TO DO

;      WAIT FOR OPERATION COMPLETE

1E5C      CLR     A
1E5D      MOV     T,A      ;RESET TIMER
1E5E      JTF     PTV17   ;CLEAR TIMER OVERFLOW FLAG
1E60      PTV17      JTF     PTV5      ;IF TIMED OUT
1E60      IN      A,P1
1E62      ANLI    A,INTRQ
1E63      JZ      PTV17   ;IF NOT COMPLETE
1E67      STOP    TCNT
1E68      SETREG  RSTA
1E6C      MOVX    A,XR0      ;READ STATUS
1E6D      ANLI    A,$3C      ;SELECT RELEVANT STATUS BITS
1E6F      JNZ     PTV5      ;IF ERROR

;      COME HERE FOR SUCCESSFUL VERIFY

1E71      PTV10      CLR     F1      ;INDICATE NO ERROR
1E71      MOVI    R0,0      ;NO DATA FRAME TO TRANSMIT
1E74      LNGJMP  SEND
;      HANDLE VERIFY TIMEOUTS AND ERRORS

1E77      PTV3       JNDRQ  PTV18
1E77      JDRQ    PTV13
1E7B      PTV18      DECR    A
1E7B      JNDRQ  PTV19
1E7C      JDRQ    PTV13
1E7E      PTV19      JNZ     PTV4      ;IF 1 SECOND TIME NOT EXHAUSTED

1E82      PTV5       STOP    TCNT
1E82      MOVI    A,FRCINT
1E85      SETREG  WCMD
1E89      MOVX    XR0,A      ;DO FORCED INTERRUPT
1E8A      PAUSE    R0,US200
1E8E      CLR     F1
1E8F      CPL     F1      ;SO HARD RETRY WILL FAIL
1E90      JUMP    HRT
;SEND ERROR, GO TO IDLE

ASSERT *<=$1F00
```

no ERRORs, 478 Labels, \$6958 free.